

Time integration: splitting methods

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outline

- what are splitting methods?
- linear splitting
ex: time-dependent Schrödinger equation
- nonlinear splitting
ex: cubic nonlinear Schrödinger equation
- extensions and references

what is splitting?

consider differential equation

$$u' = f(u) + g(u), \quad u(0) = u_0$$

divide et impera: compute (simpler) partial flows

$$v' = f(v), \quad v(0) = v_0$$

$$w' = g(w), \quad w(0) = w_0$$

$$\varphi_t(v_0) := e^{tf} v_0 := v(t)$$

$$\psi_t(w_0) := e^{tg} w_0 := w(t)$$

and define numerical solution after one step of size h by

$$u_1 = \psi_h(\varphi_h(u_0)) = e^{hg} e^{hf} u_0 \approx u(h)$$

splitting is a **one-step** method

typical problems where splitting may help

time-dependent Schrödinger eq. with smooth potential V

$$i \frac{\partial u}{\partial t} = -\Delta u + V(x, y)u$$

cubic nonlinear Schrödinger eq. (dispersive optical fibres)

$$i \frac{\partial u}{\partial x} = \frac{\partial^2 u}{\partial t^2} + \gamma |u|^2 u$$

nonlinear reaction-diffusion (advection) equations

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + g(t, u)$$

Lie and Strang splitting for a linear model

consider linear problem

$$u' = Au + Bu, \quad u(0) = u_0$$

with true solution $u(t) = e^{t(A+B)}u_0$

Lie splitting

$$u_{1,L} = e^{hA}e^{hB}u_0 \quad \text{or} \quad u_{1,L} = e^{hB}e^{hA}u_0$$

symmetric **Strang** splitting

$$u_{1,S} = e^{\frac{1}{2}hA}e^{hB}e^{\frac{1}{2}hA}u_0 \quad \text{or} \quad u_{1,S} = e^{\frac{1}{2}hB}e^{hA}e^{\frac{1}{2}hB}u_0$$

(nearly) same computational work

local error of splitting

local error = error after one time step = **splitting error**

$$\begin{aligned}u_{1,L} - u(h) &= (e^{hA}e^{hB} - e^{h(A+B)})u_0 \\ &= \left(1 + hA + \frac{h^2}{2}A^2 + \dots\right) \left(1 + hB + \frac{h^2}{2}B^2 + \dots\right) \\ &\quad - \left(1 + h(A+B) + \frac{h^2}{2}(A+B)^2 + \dots\right)u_0 \\ &= \dots = \frac{h^2}{2} [A, B]u_0 + \mathcal{O}(h^3)\end{aligned}$$

$$u_{1,S} - u(h) = h^3 \left(\frac{1}{12} [B, [B, A]] - \frac{1}{24} [A, [A, B]] \right) u_0 + \mathcal{O}(h^4)$$

commutator $[A, B] = AB - BA$

Baker-Campbell-Hausdorff formula

local error analysis

for unbounded A , **never** expand e^{tA} into a series
alternative: represent solution of

$$u' = Au + g(u), \quad u(0) = v$$

with the **variation-of-constants** formula instead

$$u(t) = e^{tA}v + \int_0^t e^{(t-s)A}g(u(s))ds$$

for the particular case $g(u) = Bu$, we get

$$e^{t(A+B)} = e^{tA} + \int_0^t e^{(t-s)A}Be^{s(A+B)}ds$$

reinsert and estimate iterated integral

local error analysis, cont.

assumptions on commutators

$$(a) \quad \|[A, B]v\| \leq c_1 \|(-A)^\alpha v\|$$

$$(b) \quad \|[A, [A, B]v]\| \leq c_2 \|(-A)^\beta v\|$$

Theorem (Jahnke, Lubich, 2000)

(i) under condition (a) with $\alpha \geq 0$

$$\|e^{\frac{1}{2}hA} e^{hB} e^{\frac{1}{2}hA} v - e^{h(A+B)} v\| \leq C_1 \cdot h^2 \cdot \|(-A)^\alpha v\|$$

(ii) under conditions (a) and (b) with $\beta \geq 1 \geq \alpha$

$$\|e^{\frac{1}{2}hA} e^{hB} e^{\frac{1}{2}hA} v - e^{h(A+B)} v\| \leq C_2 \cdot h^3 \cdot \|(-A)^\beta v\|$$

C_i only depends c_1, c_i and $\|B\|$.

stability and linear error growth

assume that

$$\|e^{tA}\| \leq 1, \quad \|e^{tB}\| \leq 1, \quad \|e^{t(A+B)}\| \leq 1$$

and set $S = e^{hA}e^{hB}$, $T = e^{t(A+B)}$. Then

$$\|S^n\| \leq \|S\|^n \leq (\|e^{tA}\| \cdot \|e^{tB}\|)^n \leq 1 \quad (\text{stability})$$

and

$$\begin{aligned} \|S^n - T^n\| &= \left\| \sum_{j=0}^{n-1} S^j (S - T) T^{n-j-1} \right\| \\ &\leq \sum_{j=0}^{n-1} \|S^j\| \cdot \|S - T\| \cdot \|T^{n-j-1}\| \leq n \|S - T\| \end{aligned}$$

convergence with linear error growth

application: time-dependent Schrödinger eq.

we have $\alpha = 1/2$ and $\beta = 1$, since

$$\begin{aligned}[A, B] \phi(x) &= \left[\frac{d^2}{dx^2}, V(x) \right] \phi(x) \\ &= (V(x)\phi(x))'' - V(x)(\phi(x))'' \\ &= V''(x)\phi(x) + 2V'(x)\phi'(x)\end{aligned}$$

this shows that $[A, B]$ is a first-order differential operator

Theorem (JL 00) Let V be C^5 -smooth. Then

$$\|U_n - U(t_n)\|_{L^2} \leq \begin{cases} C \cdot h \cdot \|U_0\|_{H^1} \\ C \cdot h^2 \cdot \|U_0\|_{H^2} \end{cases}$$

uniformly in $0 \leq nh \leq T$; the constant C depends on T , but it is independent of n and h .

implementation

determine the action of e^{hA} on a spatial vector $v(x)$ in the **Fourier** space

for example, consider

$$A = i \frac{\partial^2}{\partial x^2} \quad \text{on } (-\pi, \pi)$$

with periodic boundary conditions; thus

$$e^{hA}v = \mathcal{F}^{-1} e^{-ikh^2} \mathcal{F}v$$

efficient numerical implementation:

pseudospectral methods based on **FFT**

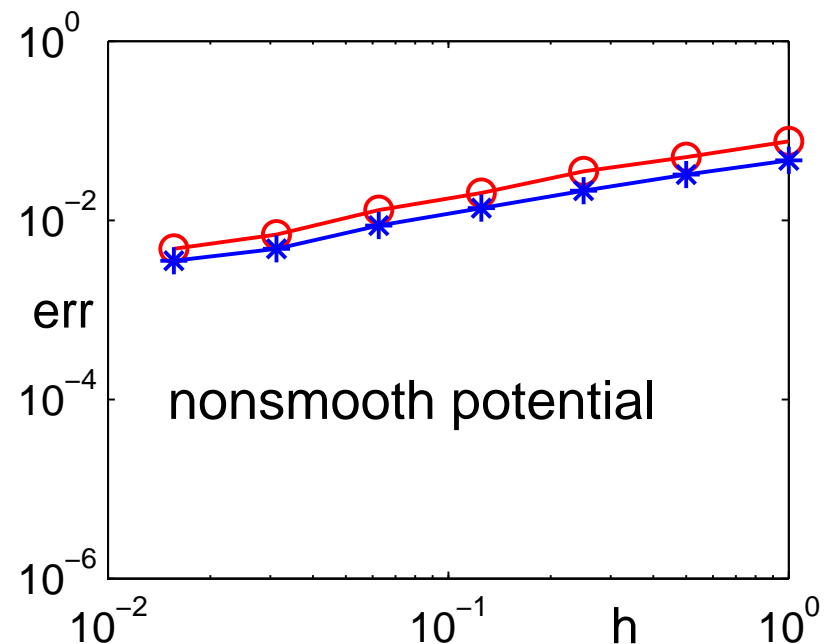
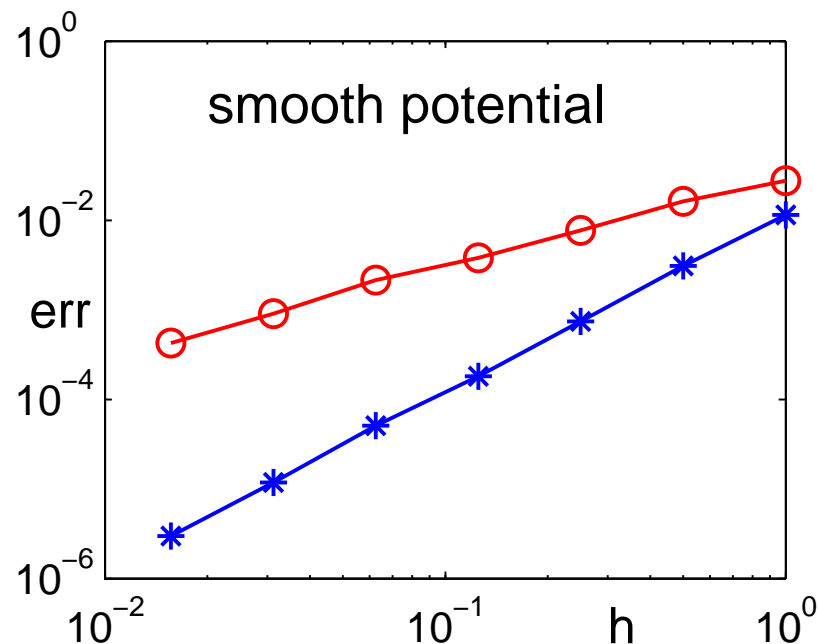
higher dimensions, Dirichlet or Neumann b.c. admissible
but restrictions on the domain

numerical experiments

smooth potential $V(x) = 1 - \cos x$ on $(-\pi, \pi)$

nonsmooth potential $V(x) = x + \pi$ on $(-\pi, \pi)$

random initial data in H^1 (red) and H^2 (blue)



experiments in line with theoretical results

nonlinear Strang splitting

consider partial differential equation

$$\frac{\partial u}{\partial t} = Au + g(u), \quad A = \Delta \quad \text{or} \quad \pm i\Delta \quad \text{or} \quad \dots$$

partial flows $\varphi_t(v) = e^{tA}v$ and $\psi_t(w_0) = w(t)$ for

$$w' = g(w), \quad w(0) = w_0$$

Strang splitting $u_{1,S} = (\varphi_{h/2} \circ \psi_h \circ \varphi_{h/2})(u_0)$

evaluation of φ by **Fourier** techniques (FFT) or by another exponential integrator

evaluation of ψ exactly or by a suitable numerical scheme (flow is local)

split-step Fourier method for NLS equation

2D cubic nonlinear Schrödinger equation

$$i \frac{\partial u}{\partial t} = \Delta u + \gamma |u|^2 u$$

Theorem (Bess et al. 2002) For sufficiently small time steps h we have

$$\|u_{n,L} - u(t_n)\|_{L^2} \leq C(\|u_0\|_{H^2}) \cdot h \cdot \|u_0\|_{H^2}$$

$$\|u_{n,S} - u(t_n)\|_{L^2} \leq C(\|u_0\|_{H^4}) \cdot h^2 \cdot \|u_0\|_{H^4}$$

uniformly in $0 \leq nh \leq T$; the constant C depends on T , but it is independent of n and h .

optimal order of convergence; constant is **not** optimal

extensions for the split-step Fourier method

- higher-order splitting methods
involve negative time-steps; only for groups
- reaction-diffusion equations

$$\frac{\partial u}{\partial t} = \Delta u + g(u)$$

ideas of Bess et al. can be adapted

- reactions $v' = g(v)$ are often very stiff
use (semi) implicit methods
stiff operator should be the last in the splitting
(Sportisse, 2000)

some references

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