

# Uniformly accurate methods for Klein-Gordon-Schrödinger and Klein-Gordon-Zahkarov systems

joint work with G. Kokkala and K. Schratz

Simon Baumstark | October 12, 2017



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## Outline



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- 2 Uniformly accurate scheme for the Klein-Gordon-Schrödinger system
- Numerical experiments
- Uniformly accurate scheme for the Klein-Gordon-Zakharov system



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Work-precision plot:



### Simulation on $x \in [0, 2\pi]$ , $t \in [0, 1]$ , $\tau_{ref} \approx 10^{-6}$ and M = 256.

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Error constant comparison w.r.t. *τ*:



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#### Limit convergence:



#### Simulation on $x \in [0, 2\pi]$ , $t \in [0, 1]$ , $\tau_{ref} \approx 10^{-6}$ and M = 256.

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#### Consider the Klein-Gordon-Schrödinger (KGS) system:

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#### Consider the Klein-Gordon-Schrödinger (KGS) system:

$$c^{-2}\partial_{tt}z(t,x) - \Delta z(t,x) + c^{2}z(t,x) = |n(t,x)|^{2},$$
  
$$i\partial_{t}n(t,x) + \Delta n(t,x) = -n(t,x)z(t,x),$$

with initial conditions

$$z(0,x) = z_0(x), \quad \partial_t z(0,x) = c^2 z_1(x), \qquad n(0,x) = n_0(x),$$

and periodic boundary conditions.



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#### Numerical Challenge:

Highly oscillatory (non-relativistic) limit regime, i.e.  $c \gg 1$ .



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#### Numerical Challenge:

Highly oscillatory (non-relativistic) limit regime, i.e.  $c \gg 1$ .

• Goal: Search numerical approx.  $z^n \approx z(t_n)$ ,  $n^n \approx n(t_n)$  with  $t_n = n\tau$ .

## **Numerical methods**



1.) Gautschi-type method:

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## Numerical methods



#### 1.) Gautschi-type method:

- Gautschi-type method for oscillatory second-order differential equations by Hochbruck/Lubich (1998)
- Here: Gautschi-type method by Bao/Dong/Zhao (2013): Exponential wave integrator pseudospectral (EWI-PS) method

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## **Numerical methods**



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Idea: Discretize Duhamel's formula (variation of constants formula).



• KGS equation  $\left(\langle \nabla \rangle_c := \sqrt{-\Delta + c^2}\right)$ :

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• KGS equation 
$$\left(\langle \nabla \rangle_c := \sqrt{-\Delta + c^2}\right)$$
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$$\partial_{tt} z(t) = -c^2 \langle \nabla \rangle_c^2 z(t) + c^2 |n(t)|^2,$$
  
$$i \partial_t n(t) = -\Delta n(t) - n(t) z(t).$$

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• Duhamel's formula (• :=  $c\langle \nabla \rangle_c \tau$ ):

$$z(t_n + \tau) = \cos(\bullet)z(t_n) + \tau \operatorname{sinc}(\bullet)z'(t_n) + c^2 \int_0^\tau \frac{\sin(c\langle \nabla \rangle_c(\tau - s))}{c\langle \nabla \rangle_c} |n(t_n + s)|^2 \, \mathrm{d}s,$$

$$n(t_n + \tau) = \mathrm{e}^{i\Delta\tau} n(t_n) + \int_0^{\tau} \mathrm{e}^{i\Delta(\tau-s)} n(t_n+s) z(t_n+s) \mathrm{d}s.$$

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• Duhamel's formula (• :=  $c\langle \nabla \rangle_c \tau$ ):

$$\begin{aligned} z(t_n+\tau) &= \cos(\bullet)z(t_n) + \tau \operatorname{sinc}(\bullet)z'(t_n) + c^2 \int_0^\tau \underbrace{\frac{\sin(c\langle \nabla \rangle_c(\tau-s))}{c\langle \nabla \rangle_c} |n(t_n+s)|^2}_{=\frac{\sin(c\langle \nabla \rangle_c(\tau-s))}{c\langle \nabla \rangle_c} |n(t_n)|^2 + \mathcal{O}(s \, \partial_t n)} \\ n(t_n+\tau) &= \operatorname{e}^{i\Delta\tau} n(t_n) + \int_0^\tau \underbrace{\operatorname{e}^{i\Delta(\tau-s)} n(t_n+s) z(t_n+s)}_{=\operatorname{e}^{i\Delta(\tau-s)} n(t_n) + \mathcal{O}(s \, (\partial_t n+\partial_t z))} \mathrm{d}s. \end{aligned}$$

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#### • Problem: large derivative $\partial_t z = \mathcal{O}(c^2)$ .



• Gautschi-type method applied to KGS system at  $t_n = 0.6$ :



**Figure:** blue line: reference solution of z ( $\tau_{ref} \approx 10^{-5}$ ), red line: numerical approximation of z ( $\tau \approx 10^{-2}$ ).



Gautschi-type method applied to KGS system at t<sub>n</sub> = 0.6:



**Figure:** blue line: reference solution of z ( $\tau_{ref} \approx 10^{-5}$ ), red line: numerical approximation of z ( $\tau \approx 10^{-2}$ ).

#### Problem: Time step restriction for large c!

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#### 2.) Limit system

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### 2.) Limit system

Idea:

Instead of solving full system, take limit approximation and solve only the **non-oscillatory** limit system.

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## 2.) Limit system

#### Idea:

Instead of solving full system, take limit approximation and solve only the non-oscillatory limit system.

Multiscale expansion yields decoupled free Schrödinger limit system

$$\begin{aligned} \partial_t u_{\infty}(t,x) &= -\frac{i}{2} \Delta u_{\infty}(t,x), \qquad u_{\infty}(0) = z_0 - i z_1, \\ \partial_t n_{\infty}(t,x) &= i \Delta n_{\infty}(t,x), \qquad n_{\infty}(0) = n_0, \end{aligned}$$

such that (for sufficiently smooth solutions)

$$z=\frac{1}{2}\left(u_{\infty}\mathrm{e}^{\mathrm{i}c^{2}t}+c.c.\right)+\mathcal{O}(c^{-2}).$$

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#### Advantage:

Non-oscillatory limit system can be solved exactly in Fourier space!





#### • Limit approximation vs. reference solution at $t_n = 0.7$ :



Figure: blue line: reference solution of z ( $\tau_{ref} \approx 10^{-5}$ ), red line: limit approximation of z ( $\tau \approx 10^{-2}$ ).



#### • Limit approximation vs. reference solution at $t_n = 0.7$ :



Figure: blue line: reference solution of z ( $\tau_{ref} \approx 10^{-5}$ ), red line: limit approximation of z ( $\tau \approx 10^{-2}$ ).

#### **Problem:** Good approximation only for $c \gg 1!$



3.) Uniformly accurate (UA) scheme by B./Kokkala/Schratz (2017)

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#### 3.) Uniformly accurate (UA) scheme by B./Kokkala/Schratz (2017)

Aim: Scheme that works well for small AND large c.

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#### 3.) Uniformly accurate (UA) scheme by B./Kokkala/Schratz (2017)

Aim: Scheme that works well for small AND large c.

Idea:

Derive Duhamel's formula in "twisted variables"

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#### Idea:

- Derive Duhamel's formula in "twisted variables"
- Integrate the highly-oscillatory phases exactly


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#### Idea:

- Derive Duhamel's formula in "twisted variables"
- Integrate the highly-oscillatory phases exactly

#### Other UA scheme:

Bao/Zhao 2013: only linear convergence rate  $\mathcal{O}( au)$  for all  $c \in [1,\infty)$ 

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• KGS as first-order system in time with  $z = \frac{1}{2}(u + \overline{u})$ 

$$i\partial_t u = -c\langle \nabla \rangle_c u + c\langle \nabla \rangle_c^{-1} |n|^2,$$
  
$$i\partial_t n = -\Delta n - \frac{1}{2}n(u + \overline{u}).$$



• KGS as first-order system in time with  $z = \frac{1}{2}(u + \overline{u})$   $i\partial_t u = -c\langle \nabla \rangle_c u + c\langle \nabla \rangle_c^{-1} |n|^2$ ,  $i\partial_t n = -\Delta n - \frac{1}{2}n(u + \overline{u})$ .

• Twisted variable 
$$u_*(t) = e^{-ic^2 t} u(t)$$
 with  $\mathcal{A}_c := c \langle \nabla \rangle_c - c^2$  satisfies  
 $i \partial_t u_* = -\mathcal{A}_c u_* + c \langle \nabla \rangle_c^{-1} |n|^2,$   
 $i \partial_t n = -\Delta n - \frac{1}{2} n \left( e^{ic^2 t} u_* + e^{-ic^2 t} \overline{u_*} \right)$ 



• KGS as first-order system in time with  $z = \frac{1}{2}(u + \overline{u})$  $i\partial_t u = -c\langle \nabla \rangle_c u + c\langle \nabla \rangle_c^{-1} |n|^2$  $i\partial_t n = -\Delta n - \frac{1}{2}n(u+\overline{u}).$ 

• Twisted variable  $u_*(t) = e^{-ic^2t}u(t)$  with  $\mathcal{A}_c := c\langle \nabla \rangle_c - c^2$  satisfies  $i\partial_t u_* = -\mathcal{A}_c u_* + c \langle \nabla \rangle_2^{-1} |n|^2$ .  $i\partial_t n = -\Delta n - \frac{1}{2}n\left(e^{ic^2t}u_* + e^{-ic^2t}\overline{u_*}\right)$ 

•  $\mathcal{A}_c$  and  $c \langle \nabla \rangle_c^{-1}$  are uniformly bounded in c:

$$\|\mathcal{A}_{c}u\|_{r}^{2} \leq \frac{1}{2}\|u\|_{r+2}^{2}, \qquad \|c\langle \nabla \rangle_{c}^{-1}u\|_{r} \leq \|u\|_{r}.$$

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• KGS as first-order system in time with  $z = \frac{1}{2}(u + \overline{u})$   $i\partial_t u = -c\langle \nabla \rangle_c u + c\langle \nabla \rangle_c^{-1} |n|^2,$  $i\partial_t n = -\Delta n - \frac{1}{2}n(u + \overline{u}).$ 

• Twisted variable  $u_*(t) = e^{-ic^2t}u(t)$  with  $\mathcal{A}_c := c\langle \nabla \rangle_c - c^2$  satisfies  $i\partial_t u_* = -\mathcal{A}_c u_* + c\langle \nabla \rangle_c^{-1} |n|^2,$  $i\partial_t n = -\Delta n - \frac{1}{2}n\left(e^{ic^2t}u_* + e^{-ic^2t}\overline{u_*}\right)$ 

•  $\mathcal{A}_c$  and  $c \langle \nabla \rangle_c^{-1}$  are uniformly bounded in *c*:

$$\|\mathcal{A}_{c}u\|_{r}^{2} \leq \frac{1}{2}\|u\|_{r+2}^{2}, \qquad \|c\langle \nabla \rangle_{c}^{-1}u\|_{r} \leq \|u\|_{r}.$$

#### Advantage:

All operators uniformly bounded in  $c \rightarrow \partial_t u_*$  uniformly bounded in c!

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#### A first-order UA scheme

Duhamel's formula yields

$$u_*(t_n + \tau) = \mathrm{e}^{i\tau\mathcal{A}_c}u_*(t_n) - ic\langle \nabla \rangle_c^{-1} \mathrm{e}^{i\tau\mathcal{A}_c} \int_0^{\tau} \mathrm{e}^{-is\mathcal{A}_c} \mathrm{e}^{-ic^2(t_n+s)} |n(t_n+s)|^2 \mathrm{d}s,$$

$$n(t_n + \tau) = \mathrm{e}^{i\tau\Delta}n(t_n) + \frac{i}{2}\mathrm{e}^{i\tau\Delta}\int_0^\tau \quad \mathrm{e}^{-is\Delta} \quad \left[\mathrm{e}^{ic^2(t_n+s)} \quad u_*(t_n+s) \quad +c.c.\right] \quad n(t_n+s) \quad \mathrm{d}s.$$



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ight] n(t_n+s) \mathrm{d}s.$$

#### Use

$$\begin{split} \mathrm{e}^{-is\mathcal{A}_c} &= 1 + \mathcal{O}(s\Delta), \qquad u_*(t_n + s) = u_*(t_n) + \mathcal{O}\left(s \,\partial_t u_*\right) \\ \mathrm{e}^{-is\Delta} &= 1 + \mathcal{O}(s\Delta), \qquad n(t_n + s) = n(t_n) + \mathcal{O}\left(s \,\partial_t n\right). \end{split}$$



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$$u_*(t_n + \tau) = e^{i\tau \mathcal{A}_c} u_*(t_n) - ic \langle \nabla \rangle_c^{-1} e^{i\tau \mathcal{A}_c} \int_0^{\tau} \underbrace{e^{-is\mathcal{A}_c}}_{=1+s\cdot\text{"nice"}} e^{-ic^2(t_n+s)} \underbrace{|n(t_n+s)|^2}_{=|n(t_n)|^2+s\cdot\text{"nice"}} \mathrm{d}s,$$
$$n(t_n + \tau) = e^{i\tau \Delta} n(t_n) + \frac{i}{2} e^{i\tau \Delta} \int_0^{\tau} \underbrace{e^{-is\Delta}}_{=1+s\cdot\text{"nice"}} \left[ e^{ic^2(t_n+s)} \underbrace{u_*(t_n+s)}_{=u_*(t_n)+s\cdot\text{"nice"}} + c.c. \right] \underbrace{n(t_n+s)}_{=n(t_n)+s\cdot\text{"nice"}} \mathrm{d}s.$$

#### Use

$$\begin{split} \mathrm{e}^{-is\mathcal{A}_c} &= 1 + \mathcal{O}(s\Delta), \qquad u_*(t_n + s) = u_*(t_n) + \mathcal{O}\left(s \,\partial_t u_*\right) \\ \mathrm{e}^{-is\Delta} &= 1 + \mathcal{O}(s\Delta), \qquad n(t_n + s) = n(t_n) + \mathcal{O}\left(s \,\partial_t n\right). \end{split}$$



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$$n(t_n + \tau) = e^{i\tau \Delta} n(t_n) + \frac{i}{2} e^{i\tau \Delta} \int_0^{\tau} \underbrace{e^{-is\Delta}}_{=1+s\cdot\text{"nice"}} \left[ e^{ic^2(t_n+s)} \underbrace{u_*(t_n+s)}_{=u_*(t_n)+s\cdot\text{"nice"}} + c.c. \right] \underbrace{n(t_n+s)}_{=n(t_n)+s\cdot\text{"nice"}} \mathrm{d}s.$$

We obtain:

$$u_*(t_n + \tau) = e^{i\tau \mathcal{A}_c} u_*(t_n) - ic \langle \nabla \rangle_c^{-1} e^{i\tau \mathcal{A}_c} \int_0^{\tau} e^{-ic^2(t_n + s)} |n(t_n)|^2 \mathrm{d}s + \mathcal{O}(\tau^2),$$
  
$$n(t_n + \tau) = e^{i\tau \Delta} n(t_n) + \frac{i}{2} e^{i\tau \Delta} \int_0^{\tau} \left[ e^{ic^2(t_n + s)} u_*(t_n) + c.c. \right] n(t_n) \mathrm{d}s + \mathcal{O}(\tau^2).$$

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#### A first-order UA scheme

Duhamel's formula yields

$$u_*(t_n + \tau) = e^{i\tau \mathcal{A}_c} u_*(t_n) - ic \langle \nabla \rangle_c^{-1} e^{i\tau \mathcal{A}_c} \int_0^{\tau} \underbrace{e^{-is\mathcal{A}_c}}_{=1+s\cdot\text{"nice"}} e^{-ic^2(t_n+s)} \underbrace{|n(t_n+s)|^2}_{=|n(t_n)|^2+s\cdot\text{"nice"}} \mathrm{d}s,$$
$$n(t_n + \tau) = e^{i\tau \Delta} n(t_n) + \frac{i}{2} e^{i\tau \Delta} \int_0^{\tau} \underbrace{e^{-is\Delta}}_{=1+s\cdot\text{"nice"}} \left[ e^{ic^2(t_n+s)} \underbrace{u_*(t_n+s)}_{=u_*(t_n)+s\cdot\text{"nice"}} + c.c. \right] \underbrace{n(t_n+s)}_{=n(t_n)+s\cdot\text{"nice"}} \mathrm{d}s.$$

We obtain:

$$u_*(t_n + \tau) = e^{i\tau \mathcal{A}_c} u_*(t_n) - ic \langle \nabla \rangle_c^{-1} e^{i\tau \mathcal{A}_c} \int_0^{\tau} e^{-ic^2(t_n + s)} |n(t_n)|^2 ds + \mathcal{O}(\tau^2),$$
  
$$n(t_n + \tau) = e^{i\tau \Delta} n(t_n) + \frac{i}{2} e^{i\tau \Delta} \int_0^{\tau} \left[ e^{ic^2(t_n + s)} u_*(t_n) + c.c. \right] n(t_n) ds + \mathcal{O}(\tau^2).$$

Now we integrate the highly-oscillatory phases  $e^{\pm ic^2(t_n+s)}$  exactly.



#### Yields first-order UA scheme:

$$u_*^{n+1} = e^{i\tau\mathcal{A}_c}u_*^n - i\tau e^{-ic^2t_n}\varphi_1(-i\tau c^2)c\langle\nabla\rangle_c^{-1}e^{i\tau\mathcal{A}_c}|n^n|^2,$$
  
$$n^{n+1} = e^{i\tau\Delta}n^n + \frac{i}{2}\tau e^{i\tau\Delta}\left[e^{ic^2t_n}\varphi_1(ic^2\tau)u_*^nn^n + e^{-ic^2t_n}\varphi_1(-ic^2\tau)\overline{u_*^n}n^n\right]$$

#### with

$$\begin{split} u^0_* &= z_0 - \textit{i} \textit{c}^{-1} \langle \nabla \rangle_{\textit{c}}^{-1} z_1, \\ n^0 &= n_0, \end{split}$$

and 
$$\varphi_1(x) := rac{\mathrm{e}^x - 1}{x}$$
.



Asymptotic convergence to the limit scheme



#### Asymptotic convergence to the limit scheme

Iteration scheme for the limit system

$$u_{\infty}^{n+1} = \mathrm{e}^{-rac{i au}{2}\Delta}u_{\infty}^{n}, \ n_{\infty}^{n+1} = \mathrm{e}^{i\Delta au}n_{\infty}^{n}.$$

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#### Asymptotic convergence to the limit scheme

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$$u_{\infty}^{n+1} = \mathrm{e}^{-rac{i au}{2}\Delta} u_{\infty}^{n}, \ n_{\infty}^{n+1} = \mathrm{e}^{i\Delta au} n_{\infty}^{n}.$$

First-order uniformly accurate scheme

$$\begin{split} u_*^{n+1} &= \mathrm{e}^{i\tau\mathcal{A}_c} u_*^n - i\tau \mathrm{e}^{-ic^2 t_n} \varphi_1(-i\tau c^2) c \langle \nabla \rangle_c^{-1} \mathrm{e}^{i\tau\mathcal{A}_c} |n^n|^2, \\ n^{n+1} &= \mathrm{e}^{i\tau\Delta} n^n + \frac{i}{2} \tau \mathrm{e}^{i\tau\Delta} \Big[ \mathrm{e}^{ic^2 t_n} \varphi_1(ic^2 \tau) u_*^n n^n + \mathrm{e}^{-ic^2 t_n} \varphi_1(-ic^2 \tau) \overline{u_*^n} n^n \Big]. \end{split}$$

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$$u_*^{n+1} = e^{i\tau\mathcal{A}_c}u_*^n - i\tau e^{-ic^2t_n}\varphi_1(-i\tau c^2)c\langle \nabla \rangle_c^{-1}e^{i\tau\mathcal{A}_c}|n^n|^2,$$
  
$$n^{n+1} = e^{i\tau\Delta}n^n + \frac{i}{2}\tau e^{i\tau\Delta} \Big[e^{ic^2t_n}\varphi_1(ic^2\tau)u_*^nn^n + e^{-ic^2t_n}\varphi_1(-ic^2\tau)\overline{u_*^n}n^n\Big].$$

With  $\|\mathcal{A}_c + \frac{1}{2}\Delta\|_r = \mathcal{O}(c^{-2})$ 

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$$\begin{split} u_*^{n+1} &= \mathrm{e}^{-\frac{i\tau}{2}\Delta} u_*^n - i\tau \mathrm{e}^{-ic^2 t_n} \varphi_1(-i\tau c^2) c \langle \nabla \rangle_c^{-1} \mathrm{e}^{-\frac{i\tau}{2}\Delta} |n^n|^2, \\ n^{n+1} &= \mathrm{e}^{i\tau\Delta} n^n + \frac{i}{2} \tau \mathrm{e}^{i\tau\Delta} \Big[ \mathrm{e}^{ic^2 t_n} \varphi_1(ic^2 \tau) u_*^n n^n + \mathrm{e}^{-ic^2 t_n} \varphi_1(-ic^2 \tau) \overline{u_*^n} n^n \Big]. \end{split}$$

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With  $\|\tau \varphi_1(i l c^2 \tau)\|_r = \mathcal{O}(c^{-2})$ , for  $l \neq 0$ 

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#### Asymptotic convergence to the limit scheme

Iteration scheme for the limit system

$$u_{\infty}^{n+1} = e^{-rac{i\tau}{2}\Delta}u_{\infty}^{n},$$
  
 $n_{\infty}^{n+1} = e^{i\Delta\tau}n_{\infty}^{n}.$ 

First-order uniformly accurate scheme

$$\begin{split} u_*^{n+1} &= \mathrm{e}^{-\frac{i\tau}{2}\Delta} u_*^n + \mathcal{O}(\boldsymbol{c}^{-2}), \\ n^{n+1} &= \mathrm{e}^{i\tau\Delta} n^n + \mathcal{O}(\boldsymbol{c}^{-2}). \end{split}$$

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Iteration scheme for the limit system

$$u_{\infty}^{n+1} = e^{-rac{i\tau}{2}\Delta}u_{\infty}^{n},$$
  
 $n_{\infty}^{n+1} = e^{i\Delta\tau}n_{\infty}^{n}.$ 

First-order uniformly accurate scheme

$$u_*^{n+1} = u_{\infty}^{n+1} + \mathcal{O}(c^{-2}),$$
  
$$n^{n+1} = n_{\infty}^{n+1} + \mathcal{O}(c^{-2}).$$



#### Theorem (Convergence bound for the first-order UA scheme)

Fix r > d/2 and assume that

$$\sup_{0 \le t \le T} \|u_*(t)\|_{r+2} + \|n_*(t)\|_{r+2} \le M.$$

For  $u_*$  defined in the first-order scheme we set

$$z^n := \frac{1}{2} \left( \mathrm{e}^{i c^2 t_n} u^n_* + \mathrm{e}^{-i c^2 t_n} \overline{u^n_*} \right).$$

Then, there exists a  $T_r > 0$  and  $\tau_0 > 0$  such that for  $\tau \le \tau_0$  and  $t_n \le T_r$  we have for all c > 0 that

$$||z(t_n) - z^n||_r + ||n(t_n) - n^n||_r \le \tau K_{r,t_n,M},$$

where the constant  $K_{r,t_n,M}$  can be chosen independently of c.

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### **Numerical experiments**



#### Order plot: First-order UA scheme:



### Simulation on $x \in [0, 2\pi]$ , $t \in [0, 0.125]$ , $\tau_{ref} \approx 10^{-7}$ and M = 256.

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### **Numerical experiments**



#### Order plot: Second-order UA scheme:



### Simulation on $x \in [0, 2\pi]$ , $t \in [0, 0.125]$ , $\tau_{ref} \approx 10^{-7}$ and M = 256.

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## Numerical experiments



#### Limit approximation:



### Simulation on $x \in [0, 2\pi]$ , $t \in [0, 1]$ , $\tau_{ref} \approx 10^{-6}$ and M = 256.

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### Klein-Gordon-Zakharov system



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### Model problem



Consider the Klein-Gordon-Zakharov (KGZ) system:

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### Model problem



Consider the Klein-Gordon-Zakharov (KGZ) system:

$$c^{-2}\partial_{tt}z - \Delta z + c^{2}z = -nz,$$
  
$$\alpha^{-2}\partial_{tt}n - \Delta n = \Delta |z|^{2}$$

with initial conditions

$$z(0) = z_0, \quad \partial_t z(0) = c^2 z_1,$$
  
 $n(0) = n_0, \quad \partial_t n(0) = \alpha n_1,$ 

in the non-singular limit regime, i.e.  $\alpha = \gamma c, \gamma \in \mathbb{R}_+$ .

### Model problem



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$$z(0) = z_0, \quad \partial_t z(0) = c^2 z_1,$$
  
 $n(0) = n_0, \quad \partial_t n(0) = \alpha n_1,$ 

in the **non-singular limit regime**, i.e.  $\alpha = \gamma c, \gamma \in \mathbb{R}_+$ .

 Derivation: We want to follow the procedure for the KGS system analogously

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#### KGZ as first-order system in time with $z = \frac{1}{2}(u + \overline{u})$ and $n = \Re(h)$

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KGZ as first-order system in time with  $z = \frac{1}{2}(u + \overline{u})$  and  $n = \Re(h)$ 

$$\begin{split} i\partial_t u &= -c \langle \nabla \rangle_c u - \frac{1}{2} c \langle \nabla \rangle_c^{-1} \Re(h) (u + \overline{u}), \\ i\partial_t h &= -\alpha \langle \nabla \rangle_0 h - \frac{1}{4} \alpha \langle \nabla \rangle_0 |u + \overline{u}|^2. \end{split}$$



KGZ as first-order system in time with  $z = \frac{1}{2}(u + \overline{u})$  and  $n = \Re(h)$ 

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#### Ansatz from MFE:

$$u_* = \mathrm{e}^{-i c^2 t} u, \qquad h_* = \mathrm{e}^{-i lpha \langle 
abla 
angle_0 t} h$$



KGZ as first-order system in time with  $z = \frac{1}{2}(u + \overline{u})$  and  $n = \Re(h)$ 

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$$u_* = \mathrm{e}^{-i c^2 t} u, \qquad h_* = \mathrm{e}^{-i lpha \langle 
abla 
angle_0 t} h$$

First-order system in u<sub>\*</sub>, h<sub>\*</sub>

$$\begin{split} i\partial_t u_* &= \mathcal{A}_c u_* - \frac{1}{2} c \langle \nabla \rangle_c^{-1} \Re \left( \mathrm{e}^{i\alpha \langle \nabla \rangle_0 t} h_* \right) \left( u_* + \mathrm{e}^{-2ic^2 t} \overline{u_*} \right) \\ i\partial_t h_* &= -\frac{\alpha}{4} \langle \nabla \rangle_0 \mathrm{e}^{-i\alpha \langle \nabla \rangle_0 t} \left( 2|u_*|^2 + \mathrm{e}^{2ic^2 t} u_*^2 + \mathrm{e}^{-2ic^2 t} \overline{u_*}^2 \right) \end{split}$$

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KGZ as first-order system in time with  $z = \frac{1}{2}(u + \overline{u})$  and  $n = \Re(h)$ 

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$$\begin{split} i\partial_t u_* &= \mathcal{A}_c u_* - \frac{1}{2} c \langle \nabla \rangle_c^{-1} \Re \big( \mathrm{e}^{i\alpha \langle \nabla \rangle_0 t} h_* \big) \big( u_* + \mathrm{e}^{-2ic^2 t} \overline{u_*} \big) \\ i\partial_t h_* &= -\frac{10}{4} \langle \nabla \rangle_0 \mathrm{e}^{-i\alpha \langle \nabla \rangle_0 t} \big( 2|u_*|^2 + \mathrm{e}^{2ic^2 t} u_*^2 + \mathrm{e}^{-2ic^2 t} \overline{u_*}^2 \big) \end{split}$$

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### **Problem**



$$i\partial_t h_* = -rac{lpha}{4} \langle 
abla 
angle_0 \mathrm{e}^{-ilpha \langle 
abla 
angle_0 t} \big( 2|u_*|^2 + \mathrm{e}^{2i\mathcal{c}^2 t} u_*^2 + \mathrm{e}^{-2i\mathcal{c}^2 t} \overline{u_*}^2 \big)$$

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### Problem



$$i\partial_t h_* = -rac{lpha}{4} \langle 
abla 
angle_0 \mathrm{e}^{-ilpha \langle 
abla 
angle_0 t} \left( 2|u_*|^2 + \mathrm{e}^{2i\mathbf{c}^2 t} u_*^2 + \mathrm{e}^{-2i\mathbf{c}^2 t} \overline{u_*}^2 
ight)$$

#### Integrating:

$$\begin{split} h_*(t_n+\tau) &= h(t_n) \\ &+ \frac{i\alpha}{4} \langle \nabla \rangle_0 \int_0^\tau e^{-i\alpha \langle \nabla \rangle_0 (t_n+s)} \Big( 2|u_*(t_n+s)|^2 + e^{2ic^2(t_n+s)} u_*^2(t_n+s) + c.c. \Big) \mathrm{d}s \end{split}$$

### Problem



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$$i\partial_t h_* = -rac{lpha}{4} \langle 
abla 
angle_0 \mathrm{e}^{-ilpha \langle 
abla 
angle_0 t} \left( 2|u_*|^2 + \mathrm{e}^{2i\mathbf{c}^2 t} u_*^2 + \mathrm{e}^{-2i\mathbf{c}^2 t} \overline{u_*}^2 
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#### Integrating:

$$\begin{split} h_*(t_n+\tau) &= h(t_n) \\ &+ \frac{i\alpha}{4} \langle \nabla \rangle_0 \int_0^\tau \mathrm{e}^{-i\alpha \langle \nabla \rangle_0 (t_n+s)} \Big( 2|u_*(t_n+s)|^2 + \mathrm{e}^{2ic^2(t_n+s)} u_*^2(t_n+s) + \mathrm{c.c.} \Big) \mathrm{d}s \end{split}$$

Taylor expansion and integrating the high oscillatory phases exactly 

$$\begin{split} h_*^{n+1} &= h_*^n + \frac{i\alpha}{4} \langle \nabla \rangle_0 \mathrm{e}^{-i\alpha \langle \nabla \rangle_0 t_n} \bigg[ 2\tau \varphi_1 \big( -i\alpha \langle \nabla \rangle_0 \tau \big) |u_*^n|^2 \\ &+ \mathrm{e}^{2ic^2 t_n} \tau \varphi_1 \big( i(-\alpha \langle \nabla \rangle_0 + 2c^2) \tau \big) (u_*^n)^2 + c.c. \bigg] \end{split}$$

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$$h_*^{n+1} = h_*^n + \frac{i\alpha}{2} \langle \nabla \rangle_0 \mathrm{e}^{-i\alpha \langle \nabla \rangle_0 t_n} \tau \varphi_1 \left( -i\alpha \langle \nabla \rangle_0 \tau \right) |u_*^n|^2$$

$$+\frac{i\alpha}{4}\langle\nabla\rangle_{0}\mathrm{e}^{-i\alpha\langle\nabla\rangle_{0}t_{n}}\Big(\mathrm{e}^{2ic^{2}t_{n}}\tau\varphi_{1}\big(i(-\alpha\langle\nabla\rangle_{0}+2c^{2})\tau\big)(u_{*}^{n})^{2}+c.c.\Big)$$

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$$h_{*}^{n+1} = h_{*}^{n} + \underbrace{\frac{i\alpha}{2} \langle \nabla \rangle_{0} e^{-i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \varphi_{1} \left( -i\alpha \langle \nabla \rangle_{0} \tau \right)}_{=:h_{1}} |u_{*}^{n}|^{2}}_{=:h_{1}} + \frac{i\alpha}{4} \langle \nabla \rangle_{0} e^{-i\alpha \langle \nabla \rangle_{0} t_{n}} \left( e^{2ic^{2}t_{n}} \tau \varphi_{1} \left( i(-\alpha \langle \nabla \rangle_{0} + 2c^{2})\tau \right) (u_{*}^{n})^{2} + c.c. \right)$$

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$$h_{*}^{n+1} = h_{*}^{n} + \underbrace{\frac{i\alpha}{2} \langle \nabla \rangle_{0} e^{-i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \varphi_{1} \left( -i\alpha \langle \nabla \rangle_{0} \tau \right)}_{=:h_{1}} |u_{*}^{n}|^{2} + \frac{i\alpha}{4} \langle \nabla \rangle_{0} e^{-i\alpha \langle \nabla \rangle_{0} t_{n}} \left( e^{2ic^{2}t_{n}} \tau \varphi_{1} \left( i(-\alpha \langle \nabla \rangle_{0} + 2c^{2}) \tau \right) (u_{*}^{n})^{2} + c.c. \right)$$

For I1 we have

$$I_{1} = \frac{i\alpha}{2} \langle \nabla \rangle_{0} \mathrm{e}^{-i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \frac{\mathrm{e}^{-i\alpha \langle \nabla \rangle_{0} \tau} - 1}{-i\alpha \langle \nabla \rangle_{0} \tau}$$

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$$h_{*}^{n+1} = h_{*}^{n} + \underbrace{\frac{i\alpha}{2} \langle \nabla \rangle_{0} e^{-i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \varphi_{1} \left( -i\alpha \langle \nabla \rangle_{0} \tau \right)}_{=:h_{1}} |u_{*}^{n}|^{2} + \frac{i\alpha}{4} \langle \nabla \rangle_{0} e^{-i\alpha \langle \nabla \rangle_{0} t_{n}} \left( e^{2ic^{2}t_{n}} \tau \varphi_{1} \left( i(-\alpha \langle \nabla \rangle_{0} + 2c^{2}) \tau \right) (u_{*}^{n})^{2} + c.c. \right)$$

For I<sub>1</sub> we have

$$\begin{split} I_{1} &= \frac{i\alpha}{2} \langle \nabla \rangle_{0} \mathrm{e}^{-i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \frac{\mathrm{e}^{-i\alpha \langle \nabla \rangle_{0} \tau} - 1}{-i\alpha \langle \nabla \rangle_{0} \tau} \\ &= \frac{1}{2} \left( \mathrm{e}^{-i\alpha \langle \nabla \rangle_{0} t_{n}} - \mathrm{e}^{-i\alpha \langle \nabla \rangle_{0} t_{n+1}} \right) \end{split}$$

### UA scheme for the KGZ system



#### First-order uniformly accurate scheme

$$\begin{split} u_*^{n+1} &= \mathrm{e}^{-i\mathcal{A}_c\tau} u_*(t_n) + \frac{i}{2} c \langle \nabla \rangle_c^{-1} \mathrm{e}^{i\tau \mathcal{A}_c} \big[ t_1^n - t_2^n \big], \\ h_*^{n+1} &= h_*^n + \frac{1}{2} \big( \mathrm{e}^{-i\alpha \langle \nabla \rangle_0 t_n} - \mathrm{e}^{-i\alpha \langle \nabla \rangle_0 t_{n+1}} \big) |u_*^n|^2 \\ &+ \frac{1}{4} \langle \nabla \rangle_0 \frac{\mathrm{e}^{-i(\alpha \langle \nabla \rangle_0 + 2c^2)\tau} - 1}{-(\langle \nabla \rangle_0 + 2c\gamma^{-1})} \mathrm{e}^{-i(\alpha \langle \nabla \rangle_0 + 2c^2) t_n} \overline{u_*^n}^2 \\ &+ \frac{1}{4} \langle \nabla \rangle_0 \frac{\mathrm{e}^{i(-\alpha \langle \nabla \rangle_0 + 2c\gamma^{-1}} - 1}{-\langle \nabla \rangle_0 + 2c\gamma^{-1}} \mathrm{e}^{i(-\alpha \langle \nabla \rangle_0 + 2c^2) t_n} (u_*^n)^2, \end{split}$$

with

$$\begin{split} l_{1}^{n} &= \frac{1}{2} \bigg[ \mathrm{e}^{i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \varphi_{1} \left( i\alpha \langle \nabla \rangle_{0} \tau \right) + \mathrm{e}^{-i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \varphi_{1} \left( -i\alpha \langle \nabla \rangle_{0} \tau \right) \bigg] \Re(h_{*}^{n}) \left( u_{*}^{n} + \mathrm{e}^{-2ic^{2}t} \overline{u_{*}^{n}} \right), \\ l_{2}^{n} &= \frac{1}{2i} \bigg[ \mathrm{e}^{i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \varphi_{1} \left( i\alpha \langle \nabla \rangle_{0} \tau \right) - \mathrm{e}^{-i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \varphi_{1} \left( -i\alpha \langle \nabla \rangle_{0} \tau \right) \bigg] \Im(h_{*}^{n}) \left( u_{*}^{n} + \mathrm{e}^{-2ic^{2}t} \overline{u_{*}^{n}} \right). \end{split}$$

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### UA scheme for the KGZ system



#### First-order uniformly accurate scheme

$$\begin{split} u_*^{n+1} &= \mathrm{e}^{-i\mathcal{A}_{c^{\tau}}} u_*(t_n) + \frac{i}{2} c \langle \nabla \rangle_c^{-1} \mathrm{e}^{i\tau \mathcal{A}_c} \big[ t_1^n - t_2^n \big], \\ h_*^{n+1} &= h_*^n + \frac{1}{2} \big( \mathrm{e}^{-i\alpha \langle \nabla \rangle_0 t_n} - \mathrm{e}^{-i\alpha \langle \nabla \rangle_0 t_{n+1}} \big) |u_*^n|^2 \\ &+ \frac{1}{4} \langle \nabla \rangle_0 \frac{\mathrm{e}^{-i(\alpha \langle \nabla \rangle_0 + 2c^2)\tau} - 1}{-(\langle \nabla \rangle_0 + 2c\gamma^{-1})} \mathrm{e}^{-i(\alpha \langle \nabla \rangle_0 + 2c^2) t_n} \overline{u_*^n}^2 \\ &+ \frac{1}{4} \langle \nabla \rangle_0 \frac{\mathrm{e}^{i(-\alpha \langle \nabla \rangle_0 + 2c^2)\tau} - 1}{-\langle \nabla \rangle_0 + 2c\gamma^{-1}} \mathrm{e}^{i(-\alpha \langle \nabla \rangle_0 + 2c^2) t_n} (u_*^n)^2, \end{split}$$

with

$$\begin{split} I_{1}^{n} &= \frac{1}{2} \bigg[ \mathrm{e}^{i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \varphi_{1} \big( i\alpha \langle \nabla \rangle_{0} \tau \big) + \mathrm{e}^{-i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \varphi_{1} \big( -i\alpha \langle \nabla \rangle_{0} \tau \big) \bigg] \Re(h_{*}^{n}) \Big( u_{*}^{n} + \mathrm{e}^{-2ic^{2}t} \overline{u_{*}^{n}} \Big), \\ I_{2}^{n} &= \frac{1}{2i} \bigg[ \mathrm{e}^{i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \varphi_{1} \big( i\alpha \langle \nabla \rangle_{0} \tau \big) - \mathrm{e}^{-i\alpha \langle \nabla \rangle_{0} t_{n}} \tau \varphi_{1} \big( -i\alpha \langle \nabla \rangle_{0} \tau \big) \bigg] \Im(h_{*}^{n}) \Big( u_{*}^{n} + \mathrm{e}^{-2ic^{2}t} \overline{u_{*}^{n}} \big). \end{split}$$

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### First numerical experiments ( $\gamma = 1$ )



Order plot:



### Simulation on $x \in [0, 2\pi]$ , $t \in [0, 1]$ , $\tau_{ref} \approx 10^{-6}$ and M = 256.

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# UA scheme for the KGZ system



#### **Questions:**

- Right twisting of h?
- Right calculation of the UA scheme?
- Convergence to the numerical scheme of the limit system?

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Remark

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#### Remark

• Derivation of the schemes for the KGZ equation also works for  $z \in \mathbb{C}$ , i.e.  $z = \frac{1}{2}(u + \overline{v})$ .



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- Generalization to higher order schemes: Insert Duhamel's formula for u<sub>\*</sub>(t<sub>n</sub> + s) into u<sub>\*</sub>(t<sub>n</sub> + τ) and go on analogously to the derivation of the first-order scheme.



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- Generalization to higher order schemes: Insert Duhamel's formula for u<sub>\*</sub>(t<sub>n</sub> + s) into u<sub>\*</sub>(t<sub>n</sub> + τ) and go on analogously to the derivation of the first-order scheme.
- For KGS also the second-order schemes converge in the limit to the corresponding second-order numerical method for the limit equation.

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### Outlook



- Work-precision plots for KGS and KGZ.
- Error analysis of the first-order scheme for the KGZ system.
- Construct higher-order methods for the KGZ system.
- Error analysis of the higher-order methods.
- Can we twist (KG, KGS, KGZ) such that  $\partial_{tt} u_{**} = \mathcal{O}(1)$ ?

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