

Implementierung der Heterogenen Multiskalenmethode in Deal II

Karlsruhe Institute of Technology (KIT)

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Methode

Code

Fehler-Plot

Vergleich zu Matlab

Ausblick

Modellproblem: (F in $L^2(\Omega)$, $0 < \eta \ll 1$)

$$\begin{cases} \text{Finde } u^\eta \in H_0^1(\Omega), \text{ sodass} \\ B^\eta(u^\eta, w) = (F, w), \forall w \in H_0^1(\Omega), \end{cases}$$

mit $B^\eta(v, w) = \int_{\Omega} a^\eta(x) \nabla v(x) \cdot \nabla w(x) dx.$

Homogenisiertes Problem:

$$\begin{cases} \text{Finde } u^{\text{eff}} \in H_0^1(\Omega), \text{ sodass} \\ B^{\text{eff}}(u^{\text{eff}}, w) = (F, w), \forall w \in H_0^1(\Omega), \end{cases}$$

mit $B^{\text{eff}}(v, w) = \int_{\Omega} a^{\text{eff}}(x) \nabla v(x) \cdot \nabla w(x) dx,$

wobei

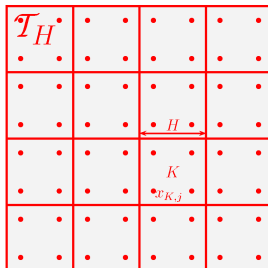
$$a^{\text{eff}}(\bar{x}) = \frac{1}{|Y_{\eta}(\bar{x})|} \int_{Y_{\eta}(\bar{x})} \left(I + D_x^T \chi \left(\bar{x}, \frac{x}{\eta} \right) \right)^T a^{\eta} \left(\bar{x}, \frac{x}{\eta} \right) \left(I + D_x^T \chi \left(\bar{x}, \frac{x}{\eta} \right) \right) dx.$$

Zellprobleme:

$$\begin{cases} -\nabla_x \cdot \left(a \left(\bar{x}, \frac{x}{\eta} \right) \left(e_i + \nabla_x \chi_i \left(\bar{x}, \frac{x}{\eta} \right) \right) \right) = 0, \text{ in } Y_{\eta} = \left(-\frac{\eta}{2}, \frac{\eta}{2} \right)^d, \\ \chi_i \text{ Y-periodisch in der zweiten Variablen.} \end{cases}$$

Diskretisierung:

$$B_H^{\text{eff}}(v_H, w_H) = \sum_{K,j} \omega_{K,j} a^{\text{eff}}(x_{K,j}) \nabla v_H(x_{K,j}) \cdot \nabla w_H(x_{K,j}) dx$$



$$B^{\text{eff}}(v, w) = \int_{\Omega} a^{\text{eff}}(x) \nabla v(x) \cdot \nabla w(x) dx$$

Diskretisierung:

$$\begin{aligned} B_H^{\text{eff}}(v_H, w_H) &= \sum_{K,j} \omega_{K,j} a^{\text{eff}}(x_{K,j}) \nabla v_H(x_{K,j}) \cdot \nabla w_H(x_{K,j}) dx \\ &= \sum_{K,j} \frac{\omega_{K,j}}{|Y_\eta|} \int_{Y_\eta(x_{K,j})} a\left(x_{K,j}, \frac{x}{\eta}\right) \left[\left(I + D_x^T \chi\left(x_{K,j}, \frac{x}{\eta}\right) \right) \nabla v_H(x_{K,j}) \right] \\ &\quad \cdot \left[\left(I + D_x^T \chi\left(x_{K,j}, \frac{x}{\eta}\right) \right) \nabla w_H(x_{K,j}) \right] dx \end{aligned}$$

$$a^{\text{eff}}(x) = \frac{1}{|Y_\eta(x)|} \int_{Y_\eta(x)} \left(I + D_x^T \chi\left(x, \frac{x}{\eta}\right) \right)^T a^\eta(x) \left(I + D_x^T \chi\left(x, \frac{x}{\eta}\right) \right) dx$$

Diskretisierung:

$$\begin{aligned} B_H^{\text{eff}}(v_H, w_H) &= \sum_{K,j} \omega_{K,j} a^{\text{eff}}(x_{K,j}) \nabla v_H(x_{K,j}) \cdot \nabla w_H(x_{K,j}) \, dx \\ &= \sum_{K,j} \frac{\omega_{K,j}}{|Y_\eta|} \int_{Y_\eta(x_{K,j})} a\left(x_{K,j}, \frac{x}{\eta}\right) \left[\left(I + D_x^T \chi\left(x_{K,j}, \frac{x}{\eta}\right) \right) \nabla v_H(x_{K,j}) \right] \\ &\quad \cdot \left[\left(I + D_x^T \chi\left(x_{K,j}, \frac{x}{\eta}\right) \right) \nabla w_H(x_{K,j}) \right] \, dx \\ &\approx \sum_{K,j} \frac{\omega_{K,j}}{|Y_\eta|} \int_{Y_\eta(x_{K,j})} a\left(x_{K,j}, \frac{x}{\eta}\right) \nabla_x \tilde{v}(x_{K,j}, x) \cdot \nabla_x \tilde{w}(x_{K,j}, x) \, dx \end{aligned}$$

Was wissen wir über \tilde{v} und \tilde{w} ?

Für \tilde{v} (bzw. \tilde{w}) gilt:

$$\nabla_x \tilde{v}(x_{K,j}, x) = \left(I + D_x^T \chi \left(x, \frac{x}{\eta} \right) \right) \nabla v_H(x_{K,j})$$

$$\tilde{v}(x_{K,j}, x) = v_{H,\text{lin}}(x_{K,j}, x)(x) + \eta \chi \left(x_{K,j}, \frac{x}{\eta} \right) \cdot \nabla v_H(x_{K,j}) + \text{const.}$$

Für \tilde{v} (bzw. \tilde{w}) gilt:

$$\nabla_x \tilde{v}(x_{K,j}, x) = \left(I + D_x^T \chi \left(x, \frac{x}{\eta} \right) \right) \nabla v_H(x_{K,j})$$

$$\tilde{v}(x_{K,j}, x) = v_{H, \text{lin}(x_{K,j}, x)}(x) + \eta \chi \left(x_{K,j}, \frac{x}{\eta} \right) \cdot \nabla v_H(x_{K,j}) + \text{const.}$$

Es folgt:

$$-\nabla_x \cdot \left(a \left(x_{K,j}, \frac{x}{\eta} \right) \nabla_x \tilde{v}(x_{K,j}, x) \right) = 0$$

$$\begin{cases} -\nabla_x \cdot \left(a \left(\bar{x}, \frac{x}{\eta} \right) \left(e_i + \nabla_x \chi_i \left(\bar{x}, \frac{x}{\eta} \right) \right) \right) = 0, \text{ in } Y_\eta = \left(-\frac{\eta}{2}, \frac{\eta}{2} \right)^d, \\ \chi_i \text{ Y-periodisch in der zweiten Variablen.} \end{cases}$$

Für \tilde{v} (bzw. \tilde{w}) gilt:

$$\nabla_x \tilde{v}(x_{K,j}, x) = \left(I + D_x^T \chi \left(x, \frac{x}{\eta} \right) \right) \nabla v_H(x_{K,j})$$

$$\tilde{v}(x_{K,j}, x) = v_{H, \text{lin}}(x_{K,j}, x)(x) + \eta \chi \left(x_{K,j}, \frac{x}{\eta} \right) \cdot \nabla v_H(x_{K,j}) + \text{const.}$$

Es folgt:

$$-\nabla_x \cdot \left(a \left(x_{K,j}, \frac{x}{\eta} \right) \nabla_x \tilde{v}(x_{K,j}, x) \right) = 0$$

$$\int_{Y_\eta(x_{K,j})} a \left(x_{K,j}, \frac{x}{\eta} \right) \nabla \tilde{v} \cdot \nabla z_h dx = 0, \forall z_h \in S_{\text{per}}^q(Y_\eta(x_{K,j}), T_h).$$

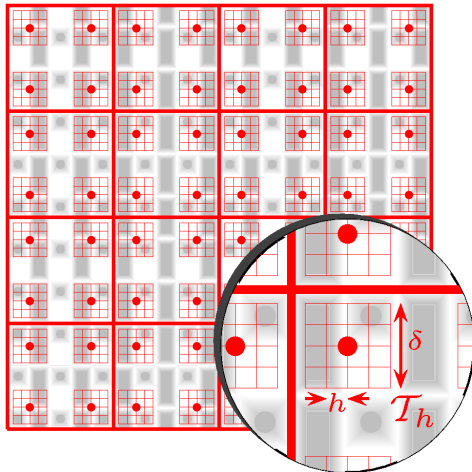
Makroproblem:

$$\begin{cases} \text{Finde } u_H \in S_0^\ell(\Omega), \text{ sodass} \\ B_H^{\text{HMM}}(u_H, w_H) = (F, w_H), \forall w_H \in S_0^\ell(\Omega), \end{cases}$$

$$\text{mit } B_H^{\text{HMM}}(v_H, w_H) = \sum_{K,j} \frac{\omega_{K,j}}{|Y_\eta|} \int_{Y_\eta(x_{K,j})} a\left(x_{K,j}, \frac{x}{\eta}\right) \nabla \tilde{v}_h(x) \cdot \nabla \tilde{w}_h(x) dx.$$

Mikroproblem:

$$\begin{cases} \text{Finde } \tilde{v}_h \in v_{H,\text{lin}}(x_{K,j})(x_{K,j}) + S_{\text{per}}^q(Y_\eta(x_{K,j}), \mathcal{T}_h), \text{ sodass} \\ \int_{Y_\eta(x_{K,j})} a\left(x_{K,j}, \frac{x}{\eta}\right) \nabla \tilde{v}_h \cdot \nabla z_h dx = 0, \forall z_h \in S_{\text{per}}^q(Y_\eta(x_{K,j}), \mathcal{T}_h). \end{cases}$$



Mikroproblem (1)

```
337 template <int dim>
338 FullMatrix<double> Micro<dim>::solve_micro (FEValues<dim>* fe_values,
339         unsigned int n_q_points, unsigned int dofs_per_cell) {
340     for (unsigned int m=0; m<n_q_points; m++) {
341         for (unsigned int n=0; n<dofs_per_cell; n++) {
342             const MultiscaleTensor<dim> multiscale_tensor_mic
343                 (fe_values->quadrature_point (m));
344             for (; cell_mic!=endc_mic; ++cell_mic) {
345                 for (unsigned int q_index=0; q_index<n_q_points_mic; ++q_index)
346                 for (unsigned int i=0; i<dofs_per_cell_mic; ++i) {
347                     for (unsigned int j=0; j<dofs_per_cell_mic; ++j)
348                         cell_matrix_mic(i,j) += fe_values_mic.shape_grad (i, q_index) *
349                             multiscale_tensor_mic.value(
350                                 fe_values_mic.quadrature_point (q_index)) *
351                                 fe_values_mic.shape_grad (j, q_index) *
352                                 fe_values_mic.JxW (q_index);
353                     cell_rhs_mic(i) -= fe_values_mic.shape_grad (i, q_index) *
354                         multiscale_tensor_mic.value(
355                             fe_values_mic.quadrature_point (q_index)) *
356                             fe_values->shape_grad(n, m) *
357                             fe_values_mic.JxW (q_index);
358                 }
359             }
360             cell_mic->get_dof_indices (local_dof_indices_mic);
361         }
362     }
363 }
```

Mikroproblem (1)

```
337 template <int dim>
338 FullMatrix<double> Micro<dim>::solve_micro (FEValues<dim>* fe_values,
339 unsigned int n_q_points, unsigned int dofs_per_cell) {
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342             const MultiscaleTensor<dim> multiscale_tensor_mic
343                 (fe_values->quadrature_point (m));
344             for (; cell_mic!=endc_mic; ++cell_mic) {
345                 for (unsigned int q_index=0; q_index<n_q_points_mic; ++q_index)
346                 for (unsigned int i=0; i<dofs_per_cell_mic; ++i) {
347                     for (unsigned int j=0; j<dofs_per_cell_mic; ++j)
348                         cell_matrix_mic(i,j) += fe_values_mic.shape_grad (i, q_index) *
349                             multiscale_tensor_mic.value(
350                                 fe_values_mic.quadrature_point (q_index)) *
351                                 fe_values_mic.shape_grad (j, q_index) *
352                                 fe_values_mic.JxW (q_index);
353                     cell_rhs_mic(i) -= fe_values_mic.shape_grad (i, q_index) *
354                         multiscale_tensor_mic.value(
355                             fe_values_mic.quadrature_point (q_index)) *
356                             fe_values->shape_grad(n, m) *
357                             fe_values_mic.JxW (q_index);
358                 }
359             }
360             cell_mic->get_dof_indices (local_dof_indices_mic);
361         }
362     }
363 }
```

Mikroproblem (2)

```
402     if (Parameters::micro_periodic_bc) {
403     } else {
404         VectorTools::interpolate boundary values (dof handler mic, 0,
405             BoundaryValuesMic<dim>(), boundary_values_mic); }
406
407     SolverControl          solver_control (1000, 1e-12);
408     SolverCG<>             solver (solver_control);
409     solver.solve (system_matrix_mic, solution_mic, system_rhs_mic,
410                 PreconditionIdentity());
411
412     if(Parameters::micro_periodic_bc)
413         constraints.distribute(solution_mic);
414
415     LinShapeFunc<dim> lin_shape_func(fe_values->quadrature_point (m),
416                                     fe_values->shape_value (n, m), fe_values->shape_grad (n, m));
417     solution_mic += lin_shape_func_fin;
418
419     for (unsigned int k=0; k<dof_handler_mic.n_dofs(); ++k)
420         solutions_mic[k][n] = solution_mic[k];
421 }
422
423 FullMatrix<double> tmp (dof_handler_mic.n_dofs(),dofs_per_cell);
424 system_matrix_mic_wo_bc full.mmult(tmp, solutions_mic);
425 tmp *= fe_values->JxW(m)/pow(Parameters::delta,dim);
426 solutions_mic.Tmmult(return_value, tmp, true);
427 }
```

Mikroproblem (2)

```
402     if (Parameters::micro_periodic_bc) {
403     } else {
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408
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414
415     if(Parameters::micro_periodic_bc)
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417
418     LinShapeFunc<dim> lin_shape_func(fe_values-&gtquadrature_point (m),
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420     solution_mic += lin_shape_func_fin;
421
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420         solutions_mic[k][n] = solution_mic[k];
421 }
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423 FullMatrix<double> tmp (dof_handler_mic.n_dofs(),dofs_per_cell);
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Makroproblem:

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$$\text{mit } B_H^{\text{HMM}}(v_H, w_H) = \sum_{K,j} \frac{\omega_{K,j}}{|Y_\eta|} \int_{Y_\eta(x_{K,j})} a\left(x_{K,j}, \frac{x}{\eta}\right) \nabla \tilde{v}_h(x) \cdot \nabla \tilde{w}_h(x) dx.$$

Mikroproblem:

$$\begin{cases} \text{Finde } \tilde{v}_h \in v_{H,\text{lin}}(x_{K,j})(x_{K,j}) + S_{\text{per}}^q(Y_\eta(x_{K,j}), \mathcal{T}_h), \text{ sodass} \\ \int_{Y_\eta(x_{K,j})} a\left(x_{K,j}, \frac{x}{\eta}\right) \nabla \tilde{v}_h \cdot \nabla z_h dx = 0, \forall z_h \in S_{\text{per}}^q(Y_\eta(x_{K,j}), \mathcal{T}_h). \end{cases}$$

```
517 template <int dim>
518 void Macro<dim>::assemble_system () {
539
540     Micro<dim> microproblem;
550
551     for (unsigned int q_index=0; q_index<n_q_points; ++q_index) {
552         for (unsigned int i=0; i<dofs_per_cell; ++i) {
558             cell_rhs(i) += (fe_values.shape_value (i, q_index) *
559                 right_hand_side.value (fe_values.quadrature_point (q_index)) *
560                 fe_values.JxW (q_index));
561         }
562     }
563     cell_matrix = microproblem.solve_micro (&fe_values, n_q_points,
564         dofs_per_cell);
568
569     cell->get_dof_indices (local_dof_indices);
570     for (unsigned int i=0; i<dofs_per_cell; ++i) {
571         for (unsigned int j=0; j<dofs_per_cell; ++j) {
572             system_matrix.add (local_dof_indices[i], local_dof_indices[j],
573                 cell_matrix(i,j));
576         }
577         system_rhs(local_dof_indices[i]) += cell_rhs(i);
578     }
579 }
```

Setup

$$\Omega = [-1, 1] \times [-1, 1]$$

$$a^\eta(x) = \begin{pmatrix} \sqrt{2} + \sin(2\pi \frac{x_1}{\eta}) & 0 \\ 0 & \sqrt{2} \end{pmatrix}$$

$$f(x) = \pi^2(1 + \sqrt{2}) \sin(\pi x_1) \sin(\pi x_2)$$

$$g_D \equiv 0 \text{ auf } \partial\Omega$$

$$\begin{cases} \text{Finde } u^\eta \in H_0^1(\Omega), \text{ sodass} \\ B^\eta(u^\eta, w) = (F, w), \forall w \in H_0^1(\Omega), \\ B^\eta(v, w) = \int_{\Omega} a^\eta(x) \nabla v(x) \cdot \nabla w(x) dx. \end{cases}$$

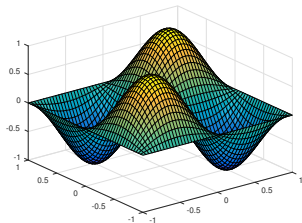
Setup

$$\Omega = [-1, 1] \times [-1, 1]$$

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$$f(x) = \pi^2(1 + \sqrt{2}) \sin(\pi x_1) \sin(\pi x_2)$$

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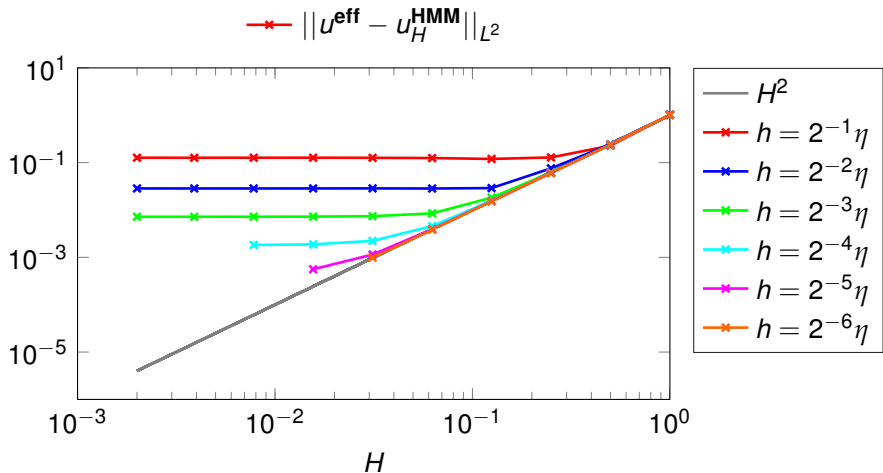


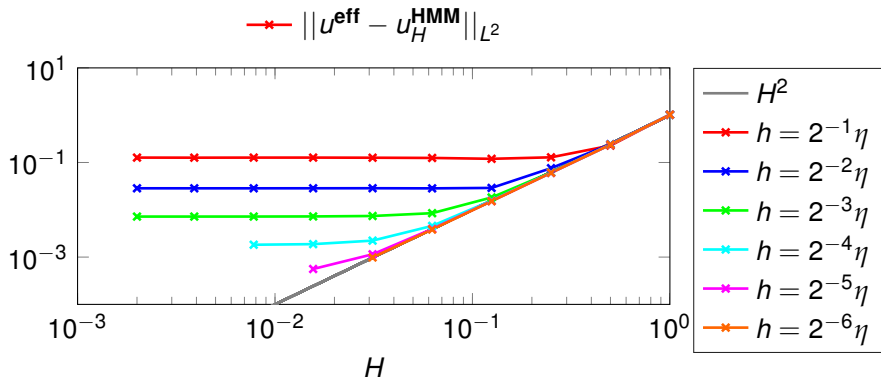
homogenisierte Lösung

$$\Rightarrow a^{\text{eff}}(x) = \begin{pmatrix} 1 & 0 \\ 0 & \sqrt{2} \end{pmatrix}$$

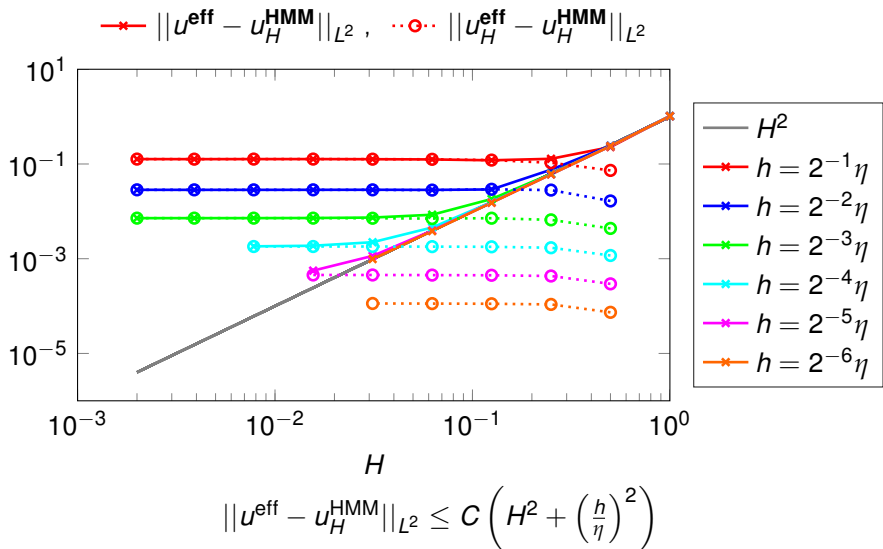
$$\Rightarrow u^{\text{eff}}(x) = \sin(\pi x_1) \sin(\pi x_2)$$

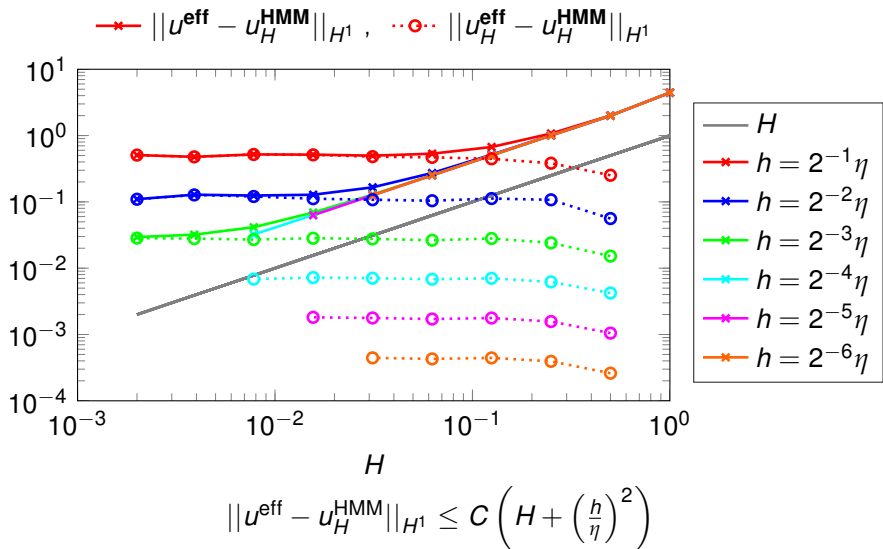
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$$||u^{\text{eff}} - u_H^{\text{HMM}}|| \leq \underbrace{||u^{\text{eff}} - u_H^{\text{eff}}||}_{e_{\text{makro}}} + \underbrace{||u_H^{\text{eff}} - u_H^{\text{HMM}}||}_{e_{\text{mikro}}}$$





Matlab-Code von A. Abdulle et al. ermöglicht:

- elliptische und parabolische Probleme, jeweils linear und nichtlinear (2009 bzw. 2011)
- Stokes-Gleichungen mit DG-FEM (2015)
- Dreiecks-, Vierecks- und gemischte Gitter

Aber dieser Code ist langsamer!

CPU: AMD FX-8320 (8 Kerne, 3.5 GHz)

RAM: DDR3 8 GB

Auflösung		Rechenzeit	
Makro	Mikro	Matlab (2009)	Deal II
4	4	ca. 58s	ca. 16s
4	5	ca. 228s	ca. 64s
5	4	ca. 225s	ca. 65s
5	5	ca. 930s	ca. 270s

- Anwendung auf Wellengleichungen und Maxwellgleichungen
- paralleles Lösen der Mikroprobleme