

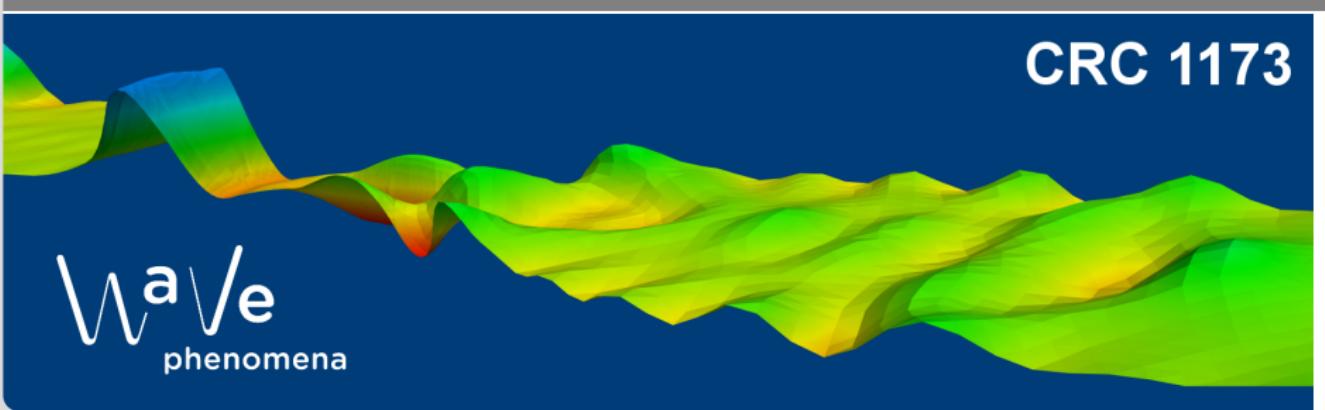
ADI splitting for the Maxwell equations

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A 3D surface plot showing complex wave patterns in a dark blue background. The surface is colored with a gradient from yellow to green, representing amplitude or intensity. The waves are highly oscillatory and non-uniform, creating a sense of depth and motion.

W a V e
phenomena

Contents

- Maxwell equations and the splitting scheme
- Properties of the numerical solution
- Numerical experiments

Maxwell Equations (MEs)

On a cuboid, say $Q := (-1, 1)^3$, we consider for $t \geq 0$

$$\begin{aligned}\partial_t(\varepsilon \mathbf{E}(t)) &= \operatorname{rot} \mathbf{H}(t) - (\sigma \mathbf{E}(t) + \mathbf{J}_0(t)), \\ \partial_t(\mu \mathbf{H}(t)) &= -\operatorname{rot} \mathbf{E}(t), \\ \operatorname{div}(\varepsilon \mathbf{E}(t)) &= \rho(t), \quad \operatorname{div}(\mu \mathbf{H}(t)) = 0, \\ \mathbf{E}(t) \times \nu &= 0, \quad \mu \mathbf{H}(t) \cdot \nu = 0, \quad \text{on } \partial Q =: \Gamma, \\ \mathbf{E}(0) &= \mathbf{E}_0, \quad \mathbf{H}(0) = \mathbf{H}_0.\end{aligned}$$

ν denotes the outer unit normal.

Given: $(\mathbf{E}_0, \mathbf{H}_0)$, \mathbf{J}_0 and $\rho(0)$

Coeffcients: $\varepsilon, \mu, \sigma \in W^{1,\infty}(Q, \mathbb{R}) \cap W^{2,3}(Q, \mathbb{R})$ and $\varepsilon, \mu \geq \delta > 0$

We look for solutions (\mathbf{E}, \mathbf{H}) in $C^1([0, \infty), L^2(Q)^6)$. Numerical analysis is done on $[0, T]$ for a $T > 0$.

Function spaces

We denote $\Gamma_1 := \{x \in \overline{Q} \mid x_1 = -1 \text{ or } x_1 = 1\}$ and Γ_2, Γ_3 analogously.

We define

$$\begin{aligned} H(Q, \text{rot}) &:= \{u \in L^2(Q)^3 \mid \text{rot } u \in L^2(Q)^3\} \quad \text{and} \\ H_0(Q, \text{rot}) &:= \{u \in H(Q, \text{rot}) \mid u \times \nu = 0\}. \end{aligned}$$

Let $X := L^2(Q)^6$ be equipped with

$$((u, v) \mid (\varphi, \psi))_X := \int_Q (\varepsilon u \cdot \varphi + \mu v \cdot \psi) \, dx$$

for all $(u, v), (\varphi, \psi) \in X$.

Function spaces

$$X = L^2(Q)^6 \quad ((u, v) \mid (\varphi, \psi))_X := \int_Q (\varepsilon u \cdot \varphi + \mu v \cdot \psi) \, dx$$

We define its subspaces

$$\begin{aligned} X_{\text{div}}^{(0)} &:= \{(u, v) \in X \mid \operatorname{div}(\mu v) = 0, \mu v \cdot v = 0 \text{ on } \Gamma, \operatorname{div}(\varepsilon u) \in L^2(Q)\}, \\ X_{\text{div}}^{(1)} &:= \{(u, v) \in X \mid \operatorname{div}(\mu v) = 0, \mu v \cdot v = 0 \text{ on } \Gamma, \operatorname{div}(\varepsilon u) \in H_0^1(Q)\}, \end{aligned}$$

being equipped with

$$\begin{aligned} \|(u, v)\|_{X_{\text{div}}^{(0)}}^2 &:= \|(u, v)\|_X^2 + \|\operatorname{div}(\varepsilon u)\|_{L^2}^2, \\ \|(u, v)\|_{X_{\text{div}}^{(1)}}^2 &:= \|(u, v)\|_X^2 + \|\operatorname{div}(\varepsilon u)\|_{H^1}^2 + \sum_{\widetilde{\Gamma} \text{ side of } Q} \|\operatorname{div}(\varepsilon u)\|_{H_0^{1/2}(\widetilde{\Gamma})}^2, \end{aligned}$$

where

$$H_0^{1/2}(\widetilde{\Gamma}) = (L^2(\widetilde{\Gamma}), H_0^1(\widetilde{\Gamma}))_{1/2,2}.$$

The Maxwell operator

(Compare [HJS, 2014]) We define the Maxwell operator

$$M := \begin{pmatrix} -\frac{\sigma}{\varepsilon} I & \frac{1}{\varepsilon} \operatorname{rot} \\ -\frac{1}{\mu} \operatorname{rot} & 0 \end{pmatrix}$$

with $D(M) := H_0(Q, \operatorname{rot}) \times H(Q, \operatorname{rot})$. Maxwell equations become

$$\partial_t \begin{pmatrix} \mathbf{E}(t) \\ \mathbf{H}(t) \end{pmatrix} = M \begin{pmatrix} \mathbf{E}(t) \\ \mathbf{H}(t) \end{pmatrix} + \begin{pmatrix} -\frac{1}{\varepsilon} \mathbf{J}_0(t) \\ 0 \end{pmatrix}$$

in X for $t \geq 0$, where $\rho(t) := \operatorname{div}(\varepsilon \mathbf{E}(t))$. We define the restrictions $M_{\operatorname{div}}^{(0)}$ and $M_{\operatorname{div}}^{(1)}$ to $X_{\operatorname{div}}^{(0)}$ and $X_{\operatorname{div}}^{(1)}$ with

$$D(M_{\operatorname{div}}^{(0)}) := D(M) \cap X_{\operatorname{div}}^{(0)} \quad \text{and} \quad D(M_{\operatorname{div}}^{(1)}) := D(M) \cap X_{\operatorname{div}}^{(1)}.$$

Observe that $M_{\operatorname{div}}^{(0)}$ maps into $X_{\operatorname{div}}^{(0)}$ and $M_{\operatorname{div}}^{(1)}$ into $X_{\operatorname{div}}^{(1)}$.

The splitting operators

(Compare [HJS, 2014]) Split $\text{rot} = C_1 - C_2$ with

$$C_1 := \begin{pmatrix} 0 & 0 & \partial_2 \\ \partial_3 & 0 & 0 \\ 0 & \partial_1 & 0 \end{pmatrix} \quad \text{and} \quad C_2 := \begin{pmatrix} 0 & \partial_3 & 0 \\ 0 & 0 & \partial_1 \\ \partial_2 & 0 & 0 \end{pmatrix}$$

and define

$$\textcolor{red}{A} := \begin{pmatrix} -\frac{\sigma}{2\varepsilon} I & \frac{1}{\varepsilon} C_1 \\ \frac{1}{\mu} C_2 & 0 \end{pmatrix} \quad \text{and} \quad \textcolor{blue}{B} := \begin{pmatrix} -\frac{\sigma}{2\varepsilon} I & -\frac{1}{\varepsilon} C_2 \\ -\frac{1}{\mu} C_1 & 0 \end{pmatrix}$$

with

$$\textcolor{red}{D(A)} := \{(u, v) \in X \mid (C_1 v, C_2 u) \in X + \text{b.c.}\} \quad \text{and}$$

$$\textcolor{blue}{D(B)} := \{(u, v) \in X \mid (C_2 v, C_1 u) \in X + \text{b.c.}\}$$

We have $M = \textcolor{red}{A} + \textcolor{blue}{B}$ on $\textcolor{red}{D(A)} \cap \textcolor{blue}{D(B)} \subseteq D(M)$.

The splitting scheme

Let $\tau > 0$ and $t_n := n\tau$ for $n \in \mathbb{N}$. We introduce (compare [OS, 2012])

$$S_{\tau,n+1}^I w := (I - \frac{\tau}{2} \textcolor{blue}{B})^{-1} (I + \frac{\tau}{2} \textcolor{red}{A}) \cdot \\ \cdot \left[(I - \frac{\tau}{2} \textcolor{red}{A})^{-1} (I + \frac{\tau}{2} \textcolor{blue}{B}) w - \frac{\tau}{2\varepsilon} (\mathbf{J}_0(t_n) + \mathbf{J}_0(t_{n+1}), 0) \right]$$

for $w \in \textcolor{blue}{D}(B)$ and suitable \mathbf{J}_0 . Note that with

$$S_{\tau,n+1}^{I,(1)} w_1 := (I - \frac{\tau}{2} \textcolor{red}{A})^{-1} (I + \frac{\tau}{2} \textcolor{blue}{B}) w_1 \quad \text{for } w_1 \in \textcolor{blue}{D}(B) \quad \text{and}$$

$$S_{\tau,n+1}^{I,(2)} w_2 := (I - \frac{\tau}{2} \textcolor{blue}{B})^{-1} (I + \frac{\tau}{2} \textcolor{red}{A}) w_2 \quad \text{for } w_2 \in \textcolor{red}{D}(A)$$

we can write

$$S_{\tau,n+1}^I w = S_{\tau,n+1}^{I,(2)} \left[S_{\tau,n+1}^{I,(1)} w - \frac{\tau}{2\varepsilon} (\mathbf{J}_0(t_n) + \mathbf{J}_0(t_{n+1}), 0) \right].$$

Proposition 1

$M_{\text{div}}^{(0)}$ generates a C_0 -semigroup on $X_{\text{div}}^{(0)}$, giving the unique solution of (MEs) in $C^1([0, \infty), X_{\text{div}}^{(0)}) \cap C([0, \infty), D(M_{\text{div}}^{(0)}))$ if $(\mathbf{J}_0, 0) \in C([0, \infty), D(M_{\text{div}}^{(0)}))$ and $(\mathbf{E}_0, \mathbf{H}_0) \in D(M_{\text{div}}^{(0)})$.

Solutions to the Maxwell equations in $X_{\text{div}}^{(0)}$

Proposition 1

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Proposition 2

$M_{\text{div}}^{(1)}$ generates a C_0 -semigroup on $X_{\text{div}}^{(1)}$, giving the unique solution of (MEs) in $C^1([0, \infty), X_{\text{div}}^{(1)}) \cap C([0, \infty), D(M_{\text{div}}^{(1)}))$ if $(\mathbf{J}_0, 0) \in C([0, \infty), D(M_{\text{div}}^{(1)}))$ and $(\mathbf{E}_0, \mathbf{H}_0) \in D(M_{\text{div}}^{(1)})$.

Efficiency of the scheme

From $(\mathbf{E}_{n+1/2}, \mathbf{H}_{n+1/2}) := S_{\tau, n+1}^{I, (1)}(\mathbf{E}_n, \mathbf{H}_n) = (I - \frac{\tau}{2}A)^{-1}(I + \frac{\tau}{2}B)(\mathbf{E}_n, \mathbf{H}_n)$ we get

$$(1 + \frac{\sigma\tau}{4\varepsilon})\mathbf{E}_{n+1/2} = (1 - \frac{\sigma\tau}{2\varepsilon})\mathbf{E}_n - \frac{\tau}{2\varepsilon}C_2\mathbf{H}_n + \frac{\tau}{2\varepsilon}C_1\mathbf{H}_{n+1/2},$$

$$\mathbf{H}_{n+1/2} = \mathbf{H}_n - \frac{\tau}{2\mu}C_1\mathbf{E}_n + \frac{\tau}{2\mu}C_2\mathbf{E}_{n+1/2}.$$

Efficiency of the scheme

From $(\mathbf{E}_{n+1/2}, \mathbf{H}_{n+1/2}) := S_{\tau, n+1}^{I, (1)}(\mathbf{E}_n, \mathbf{H}_n) = (I - \frac{\tau}{2}A)^{-1}(I + \frac{\tau}{2}B)(\mathbf{E}_n, \mathbf{H}_n)$ we get

$$(1 + \frac{\sigma\tau}{4\varepsilon})\mathbf{E}_{n+1/2} = (1 - \frac{\sigma\tau}{2\varepsilon})\mathbf{E}_n - \frac{\tau}{2\varepsilon}C_2\mathbf{H}_n + \frac{\tau}{2\varepsilon}C_1\mathbf{H}_{n+1/2},$$

$$\mathbf{H}_{n+1/2} = \mathbf{H}_n - \frac{\tau}{2\mu}C_1\mathbf{E}_n + \frac{\tau}{2\mu}C_2\mathbf{E}_{n+1/2}.$$

Plugging the second equation into the first one yields

$$\left((1 + \frac{\sigma\tau}{4\varepsilon})I - \frac{\tau^2}{4\varepsilon}D_\mu^{(1)}\right)\mathbf{E}_{n+1/2} = (1 - \frac{\sigma\tau}{2\varepsilon})\mathbf{E}_n + \frac{\tau}{2\varepsilon}\operatorname{rot}\mathbf{H}_n + \frac{\tau}{2\varepsilon}C_1\mathbf{H}_n - \frac{\tau^2}{4\varepsilon}C_1\frac{1}{\mu}C_1\mathbf{E}_n,$$

$$\mathbf{H}_{n+1/2} = \mathbf{H}_n - \frac{\tau}{2\mu}C_1\mathbf{E}_n + \frac{\tau}{2\mu}C_2\mathbf{E}_{n+1/2},$$

with

$$D_\mu^{(1)} := C_1\frac{1}{\mu}C_2 = \begin{pmatrix} \partial_2\frac{1}{\mu}\partial_2 & 0 & 0 \\ 0 & \partial_3\frac{1}{\mu}\partial_3 & 0 \\ 0 & 0 & \partial_1\frac{1}{\mu}\partial_1 \end{pmatrix}.$$

Efficiency of the scheme

$$\begin{aligned} \left((1 + \frac{\sigma\tau}{4\varepsilon})I - \frac{\tau^2}{4\varepsilon} D_{\mu}^{(1)} \right) \mathbf{E}_{n+1/2} &= (1 - \frac{\sigma\tau}{2\varepsilon}) \mathbf{E}_n + \frac{\tau}{2\varepsilon} \operatorname{rot} \mathbf{H}_n + \frac{\tau}{2\varepsilon} C_1 \mathbf{H}_n \\ &\quad - \frac{\tau^2}{4\varepsilon} C_1 \frac{1}{\mu} C_1 \mathbf{E}_n, \\ \mathbf{H}_{n+1/2} &= \mathbf{H}_n - \frac{\tau}{2\mu} C_1 \mathbf{E}_n + \frac{\tau}{2\mu} C_2 \mathbf{E}_{n+1/2}, \end{aligned}$$

with

$$D_{\mu}^{(1)} := C_1 \frac{1}{\mu} C_2 = \begin{pmatrix} \partial_2 \frac{1}{\mu} \partial_2 & 0 & 0 \\ 0 & \partial_3 \frac{1}{\mu} \partial_3 & 0 \\ 0 & 0 & \partial_1 \frac{1}{\mu} \partial_1 \end{pmatrix}.$$

⇒ Implicit first equation decouples into three one-dimensional equations!
(See Namiki '99, Chen/Zhang/Zheng '00 for the case $\sigma = 0$.)

The second half step is treated similarly after adding the inhomogeneity.

(Nearly) preservation of the divergence

Theorem 1 (Preservation of the divergence) (E., Schnaubelt, 2016)

Let $(\mathbf{J}_0, 0) \in C([0, T], D((M_{\text{div}}^{(1)})^2)) \cap C^2([0, T], D(M_{\text{div}}^{(1)}))$ and $(\mathbf{E}_0, \mathbf{H}_0) \in D((M_{\text{div}}^{(1)})^2)$. Then there exists a $\tau_0 > 0$ s.t. for all $0 < \tau \leq \tau_0$ and $N \in \mathbb{N}$ with $N\tau \leq T$ we have

$$\begin{aligned} & \left\| \left((\text{div}(\varepsilon \mathbf{E}_N), \text{div}(\mu \mathbf{H}_N)) - (\text{div}(\varepsilon \mathbf{E}_0), 0) + \int_0^{N\tau} (\text{div}(\mathbf{J}_0(s)), 0) ds \right. \right. \\ & \quad \left. \left. + \sum_{k=0}^{N-1} \frac{\tau}{2} (\text{div}(\frac{\sigma}{2} \mathbf{E}_{k+1} + \sigma \mathbf{E}_{k+1/2} + \frac{\sigma}{2} \mathbf{E}_k), 0) \right) \right\|_{H^{-1}} \\ & \leq C\tau \end{aligned}$$

for a constant C only depending on $(\mathbf{E}_0, \mathbf{H}_0)$, \mathbf{J}_0 , ε , μ , σ and T .

Theorem 2 (Strong convergence) (E., Schnaubelt, 2016)

Let $(\mathbf{J}_0, 0) \in C([0, T], D((M_{\text{div}}^{(1)})^2)) \cap C^2([0, T], D(M_{\text{div}}^{(1)}))$ and $(\mathbf{E}_0, \mathbf{H}_0) \in D((M_{\text{div}}^{(1)})^3)$. Then for all $\tau > 0$ and $n \in \mathbb{N}$ with $n\tau \leq T$ we have

$$\|S_{\tau,n}^I \cdots S_{\tau,1}^I(\mathbf{E}_0, \mathbf{H}_0) - (\mathbf{E}(n\tau), \mathbf{H}(n\tau))\|_{L^2} \leq C\tau^2$$

with a constant C depending only on $(\mathbf{E}_0, \mathbf{H}_0)$, \mathbf{J}_0 , ε , μ , σ and T .

Weak convergence of the scheme

Define

$$Y := \{(u, v) \in (H^1(Q))^6 \mid u_j = 0 \text{ on } \Gamma \setminus \Gamma_j, v_j = 0 \text{ on } \Gamma_j, \text{ for all } j \in \{1, 2, 3\}\}.$$

Theorem 3 (Weak convergence) (E., Schnaubelt, 2016)

Let $(\mathbf{J}_0, 0) \in C([0, T], D((M_{\text{div}}^{(0)}))) \cap C^2([0, T], X_{\text{div}}^{(0)})$ and $(\mathbf{E}_0, \mathbf{H}_0) \in D((M_{\text{div}}^{(0)})^2)$. Then for all $\tau > 0$ and $n \in \mathbb{N}$ with $n\tau \leq T$ we have

$$\left| \langle S_{\tau,n}^I \cdots S_{\tau,1}^I (\mathbf{E}_0, \mathbf{H}_0) - (\mathbf{E}(n\tau), \mathbf{H}(n\tau)), (\varphi, \psi) \rangle_Y \right| \leq C\tau^2$$

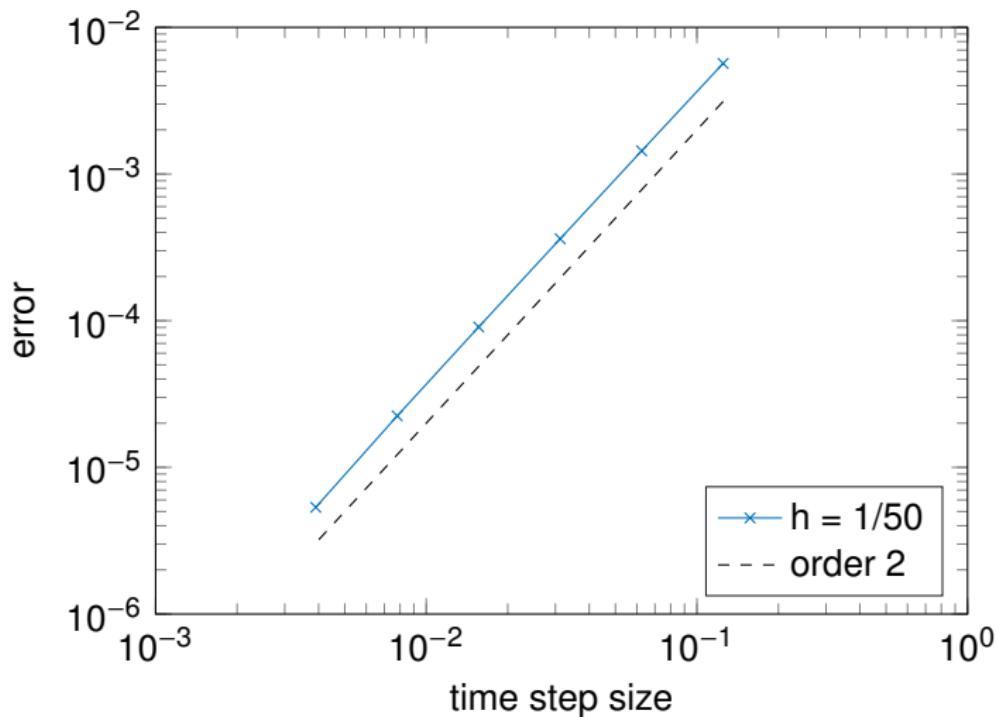
for all $(\varphi, \psi) \in Y$ with a constant C depending only on $(\mathbf{E}_0, \mathbf{H}_0)$, \mathbf{J}_0 , ε , μ , σ and T .

Numerical experiments (I)

- spatial domain $Q = (0, 1)^3$, discretized by the Yee grid with 50 grid points per direction
- time domain $[0, 1]$
- time steps size 2^{-k} , $k = 3, \dots, 8$
- reference solution: ADI method with time step size 2^{-10}
- ε, μ, σ smooth (arctan)
- \mathbf{J}_0 smooth in space (mollifier) and time (trigonometric)
- $(\mathbf{E}_0, \mathbf{H}_0)$ smooth in space and time (trigonometric)

Numerical experiments (II)

Error of the ADI splitting



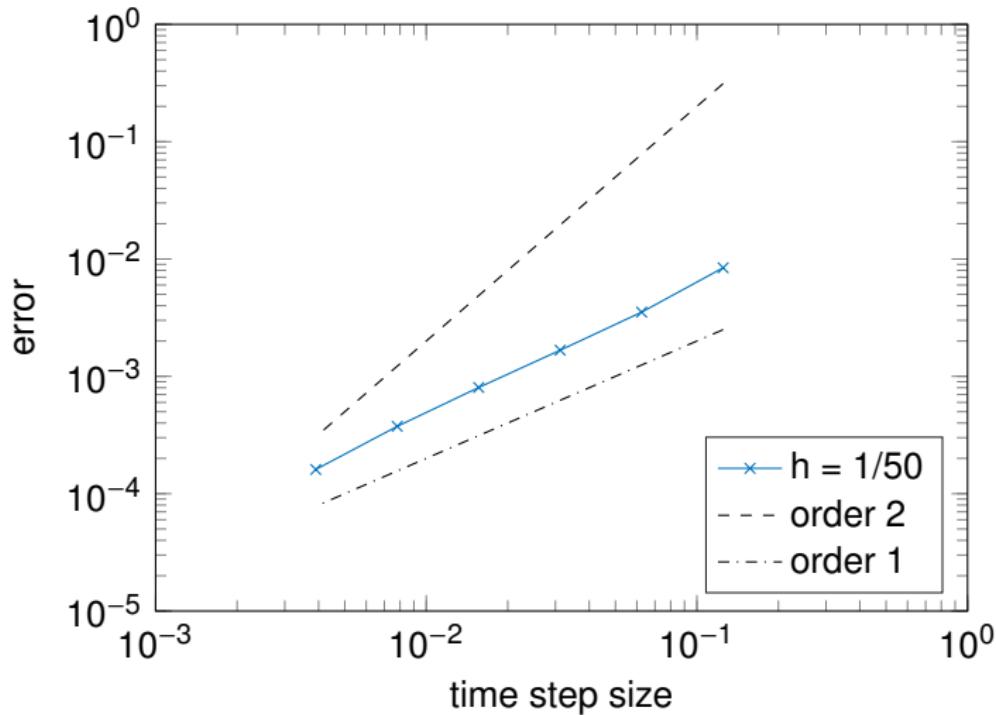
Numerical experiments (III)

Reduction of the convergence order:

- Choose \mathbf{J}_0 smooth of the type \arctan in space.
⇒ Does not fulfill the boundary conditions of $D((M_{\text{div}}^{(1)})^2)$.
- Choose $(\mathbf{E}_0, \mathbf{H}_0)$ smooth so that it does not fulfill the boundary conditions (in space) of $D((M_{\text{div}}^{(1)})^3)$.

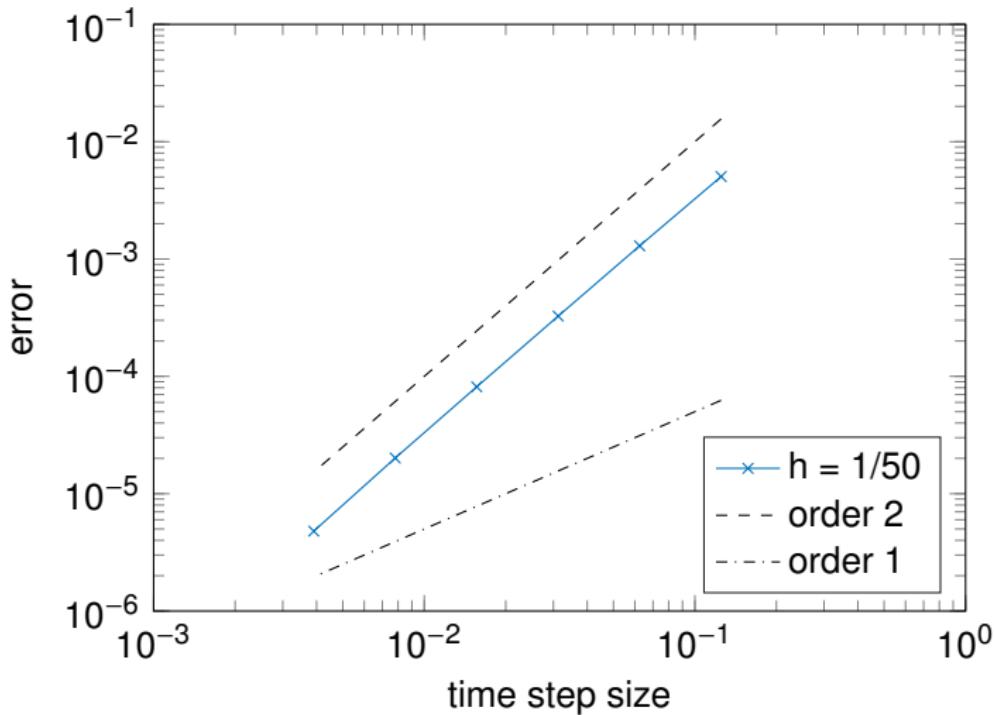
Numerical experiments (IV)

Error of the ADI splitting



Numerical experiments (V)

Error of the ADI splitting



Results:

- Second order convergence in L^2 and in " H^{-1} "
- First order preservation of the divergence in H^{-1}
- Numerical confirmation of the convergence order
- Order reduction for violated boundary conditions of \mathbf{J}_0

Aims of further research:

- Order reduction for violated boundary conditions of $(\mathbf{E}_0, \mathbf{H}_0)$
- Numerical confirmation of the divergence preservation
- Generalizations of the domain to unions of cuboids
- Piecewise smooth coefficients
- Analysis of the space discretisation